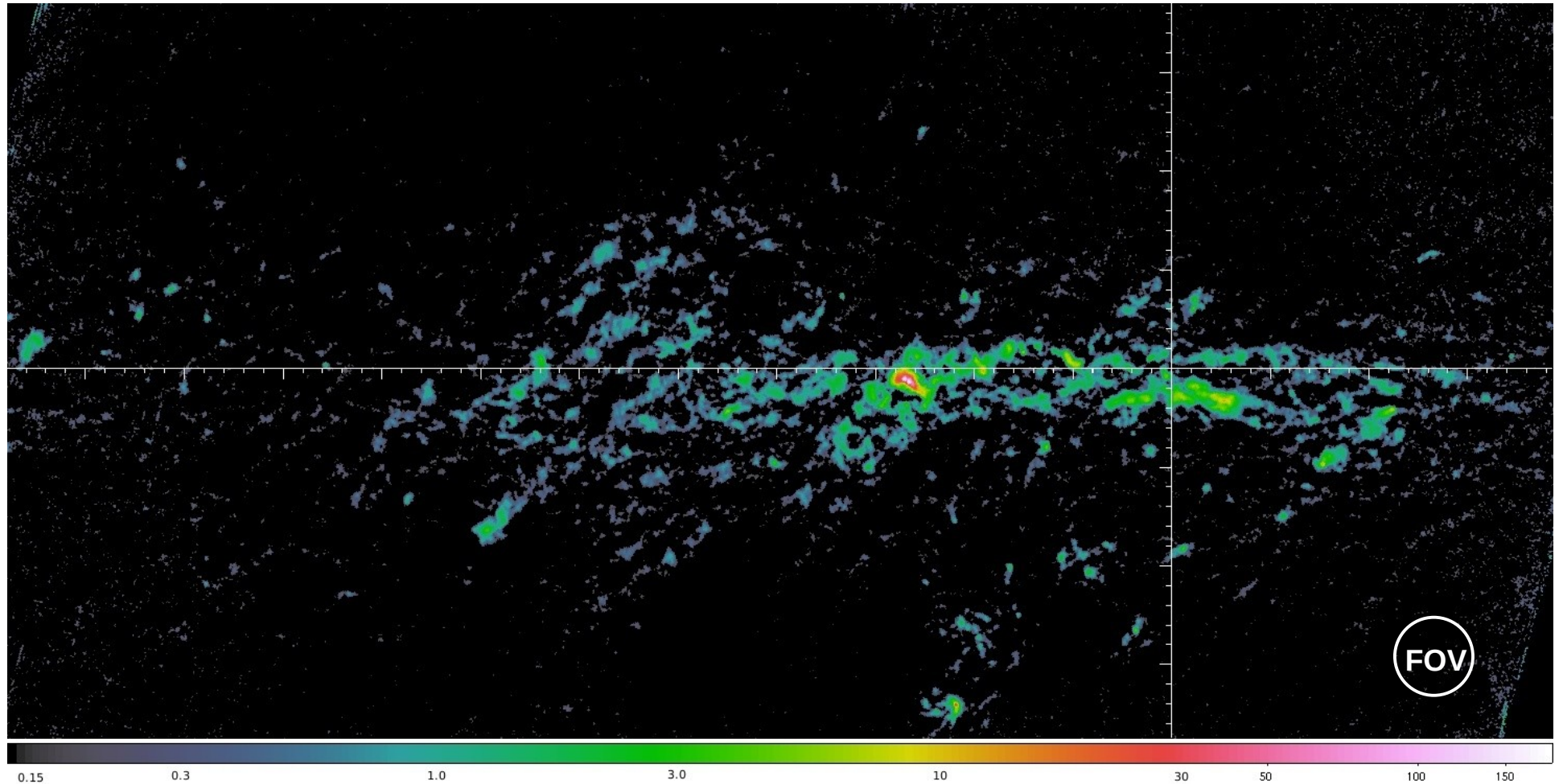


# Scanning Strategies for Imaging Arrays

Attila Kovács  
MPI for Radioastronomy



Max-Planck-Institut  
für  
Radioastronomie



# Chopping

## *Differential Signals*

Fast switching of detectors between source and blank sky.  
Analyze difference signals.

*E.g. 45" switching at 4 Hz for SHARC*

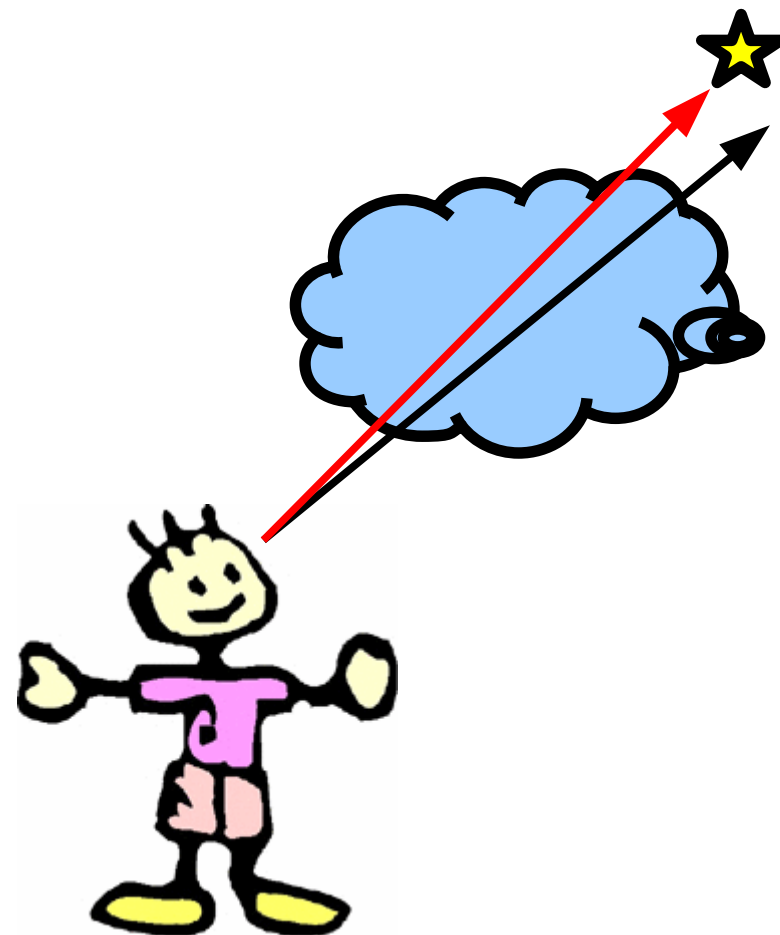
### Problems

**Differencing Noise**  
*(2x observing time)*

**Insensitivity to Certain  
Spatial Components**

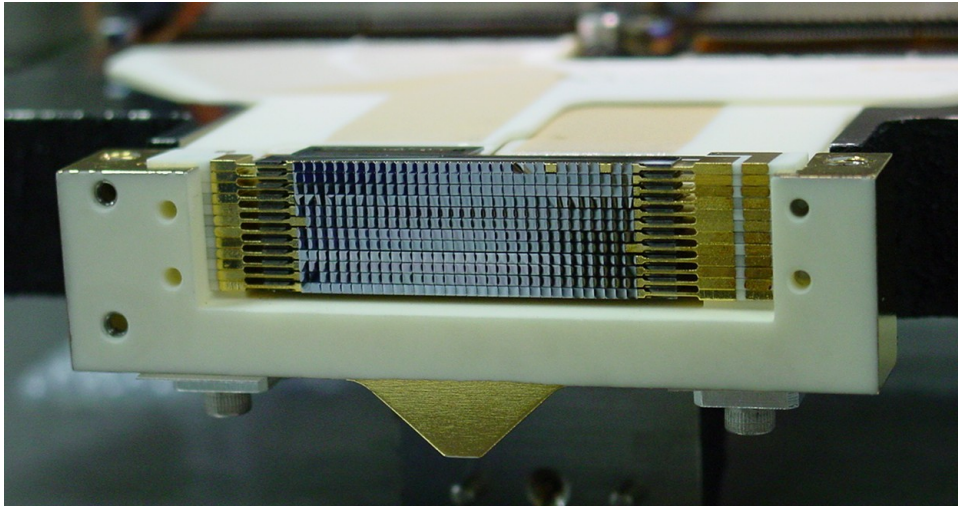
**Duty Cycle**

**Striping**  
*(Imperfect Sky Removal)*

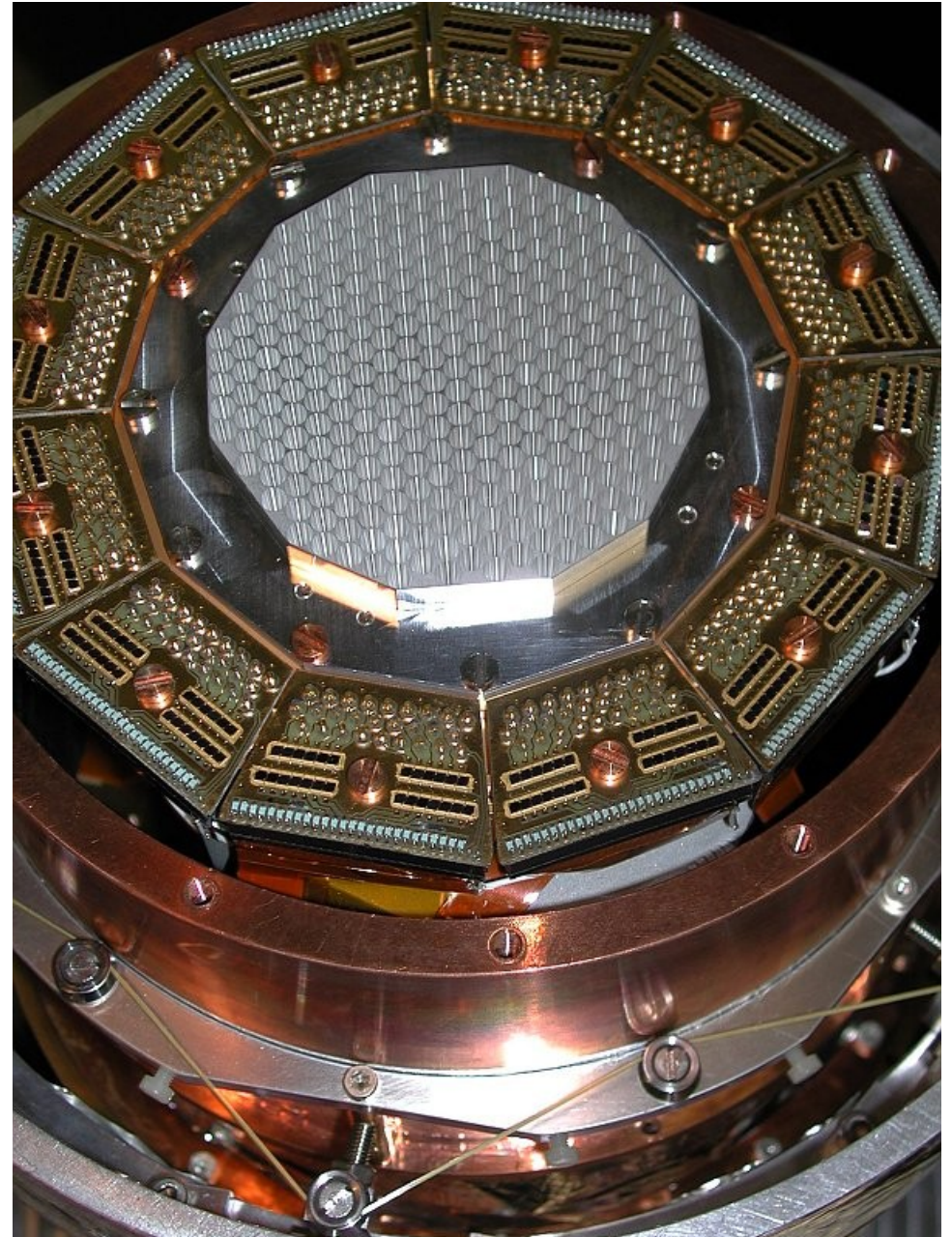


# Large Arrays

SHARC-2



LABOCA



Poster on data reduction on Friday!

# Observing Mode Wish List

---

Noise Resistance (esp.  $1/f$ )

Large-Scale Sensitivity

Coverage

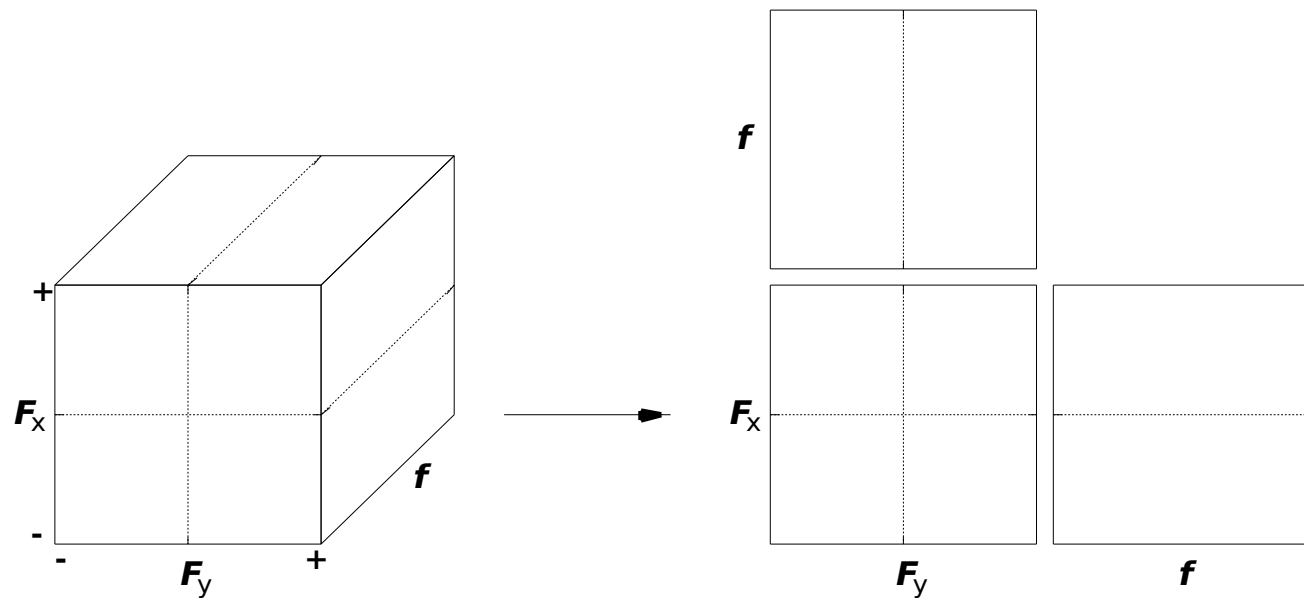
Dynamic Range

Feasibility of Implementation

# Noise Resistance

## *Spectral Noise Locations*

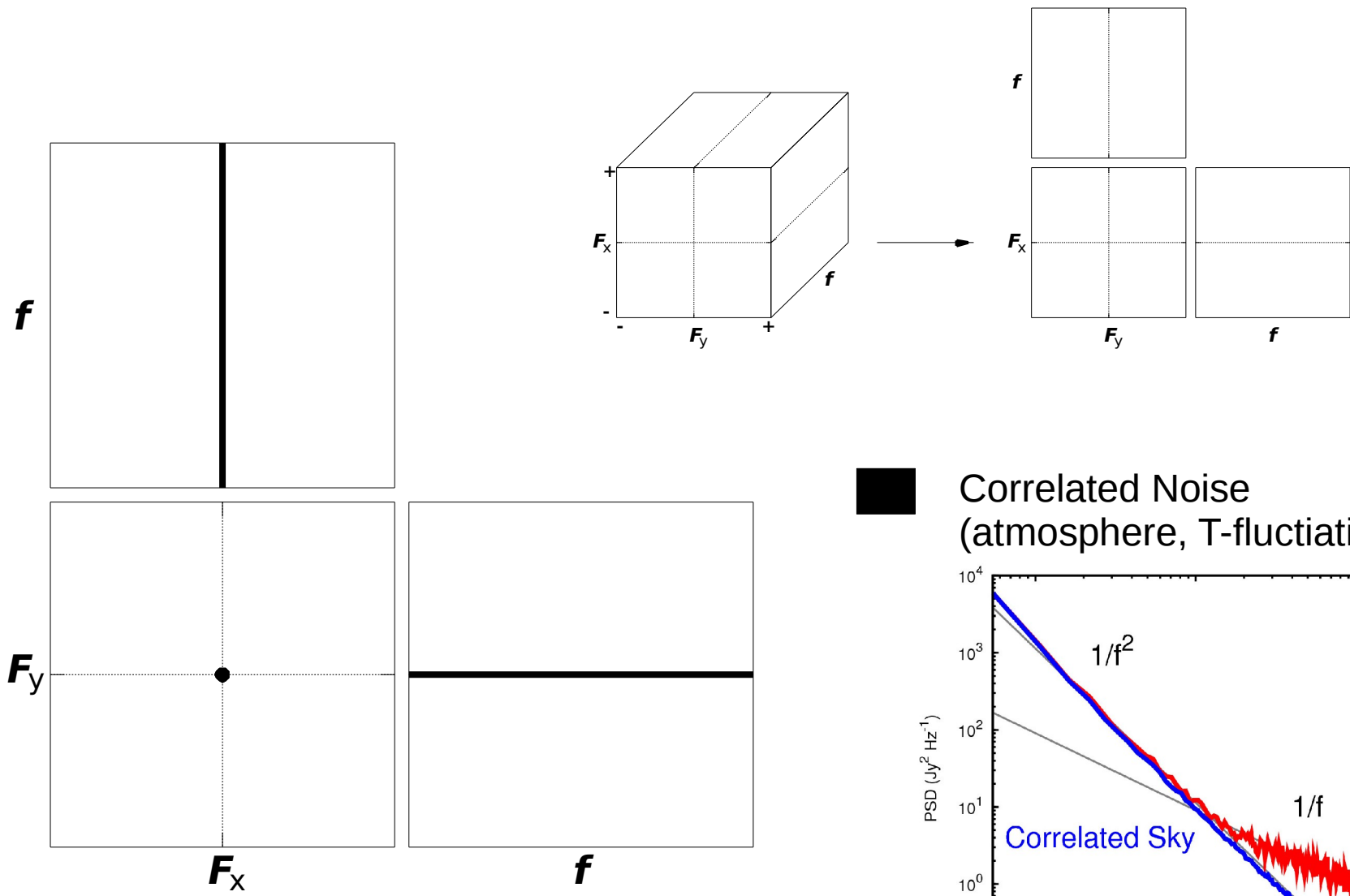
Stationary noise (in time and in space) is characterized by its power spectrum of independent components.



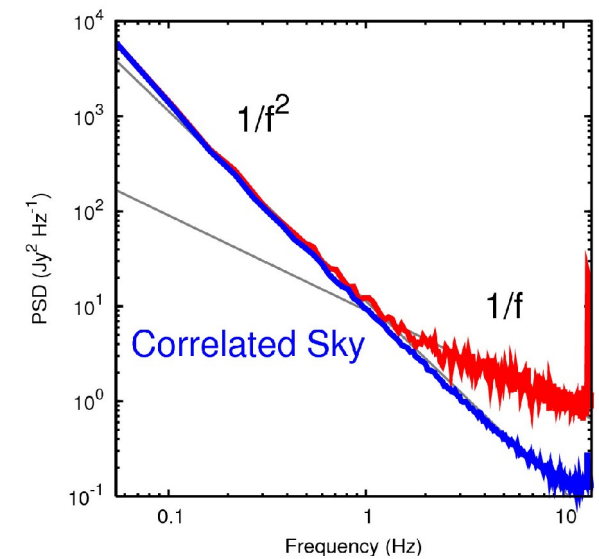
*Projections of a spectral cube*

# Noise Resistance

## *Spectral Noise Locations*

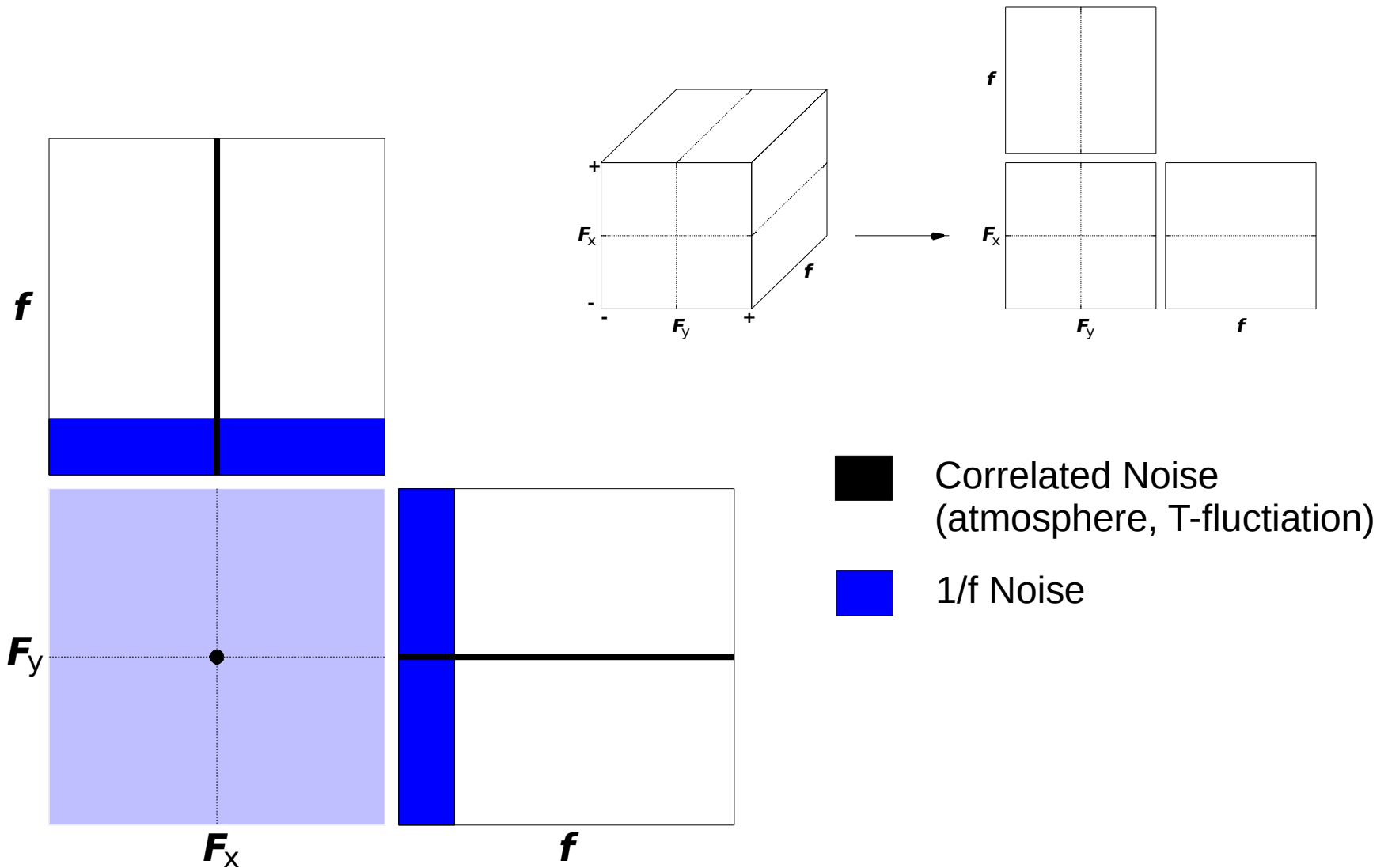


■ Correlated Noise  
(atmosphere, T-fluctuation)



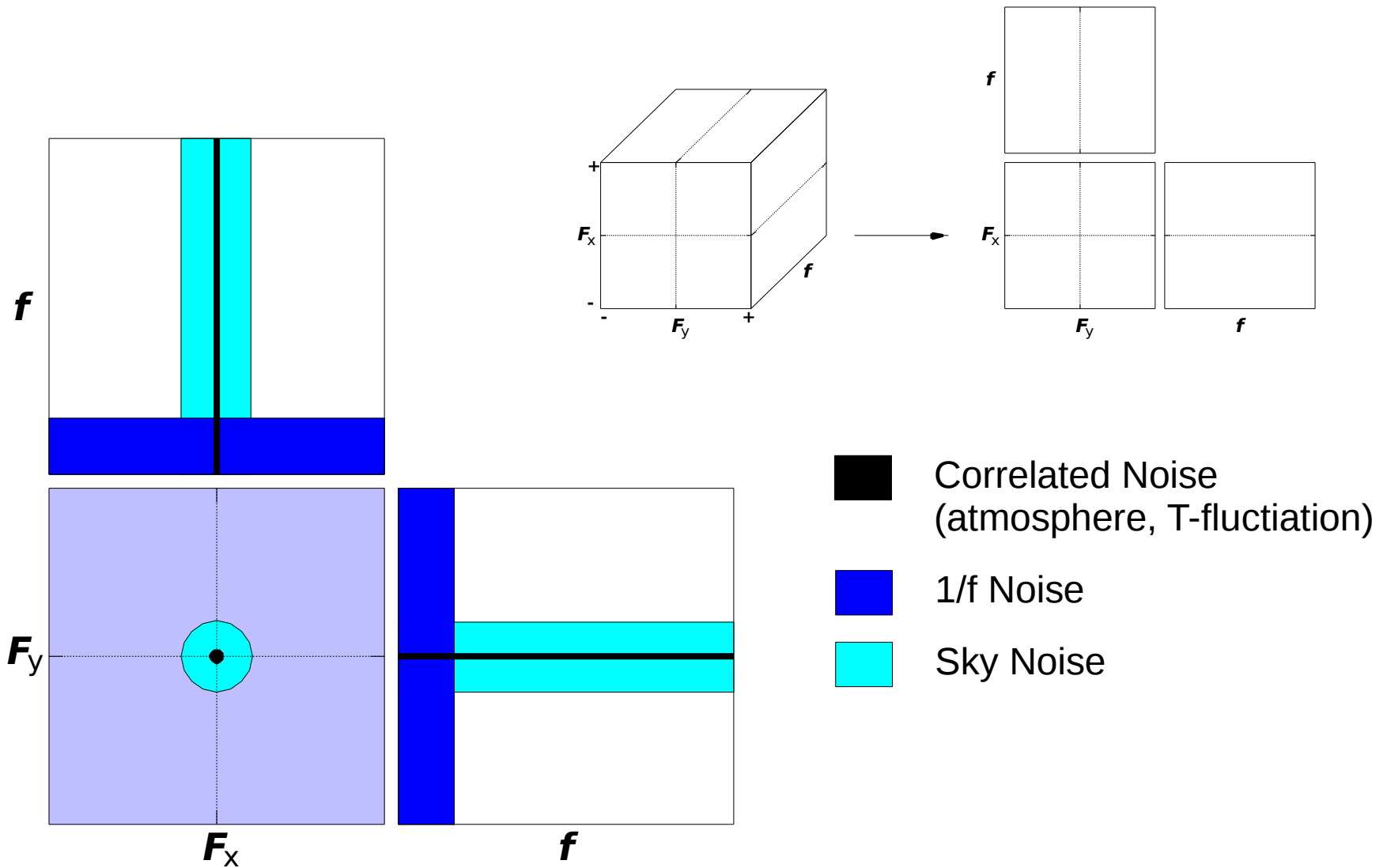
# Noise Resistance

## *Spectral Noise Locations*



# Noise Resistance

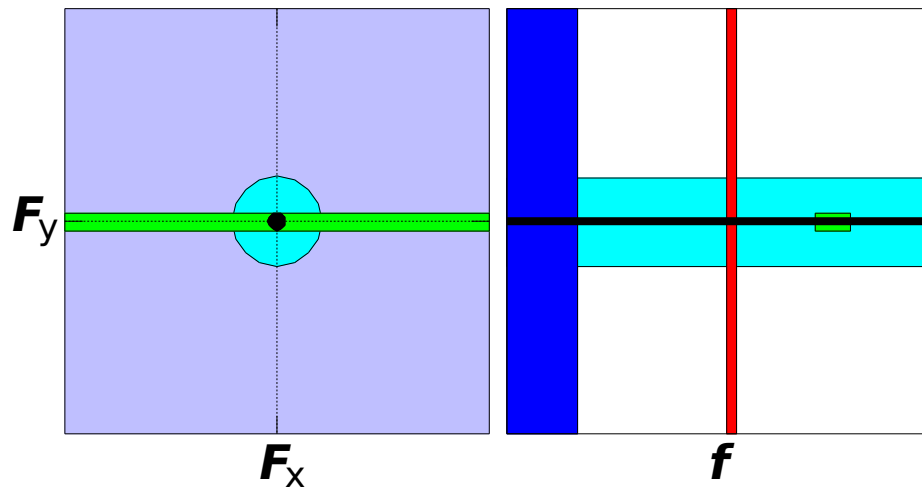
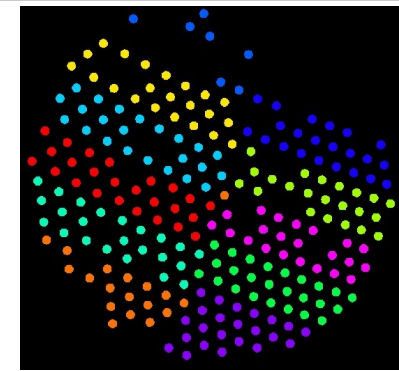
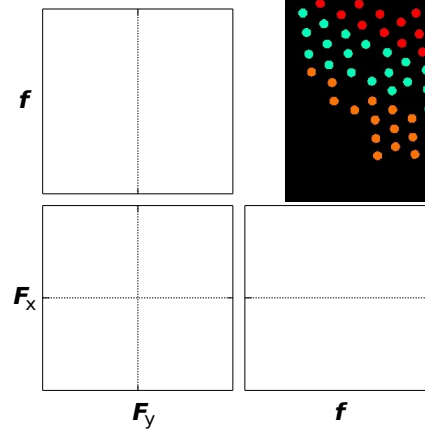
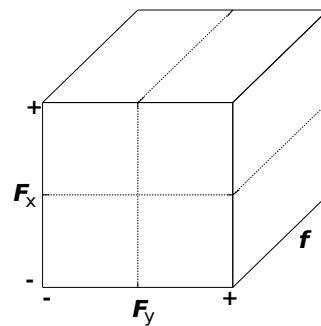
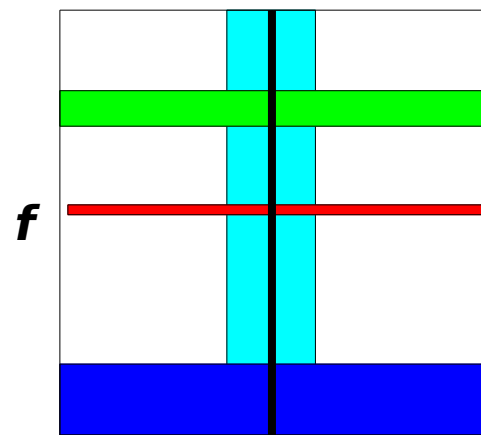
## *Spectral Noise Locations*










# Noise Resistance

## *Spectral Noise Locations*

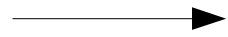


-  Correlated Noise (atmosphere, T-fluctuation)
-  1/f Noise
-  Sky Noise
-  Narrow-band Resonance (isotropic)
-  Wide-band Resonance (oriented)

# Noise Resistance

## *Strategies*

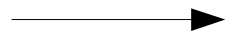
**1/f Noise**



Spread signals into the higher frequencies...

**Faster Scanning**

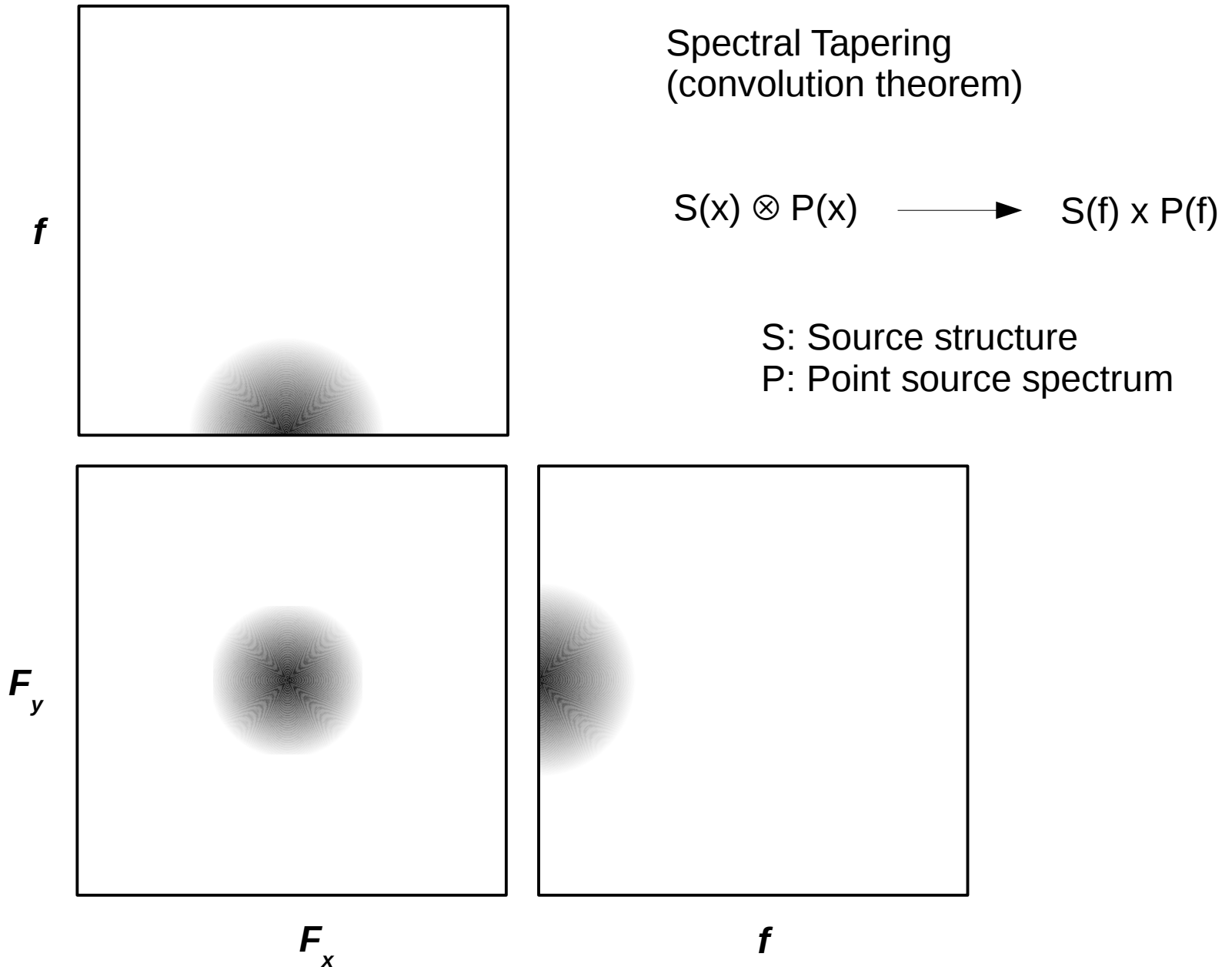
**Generic  
Noise**



Spread signals widely...

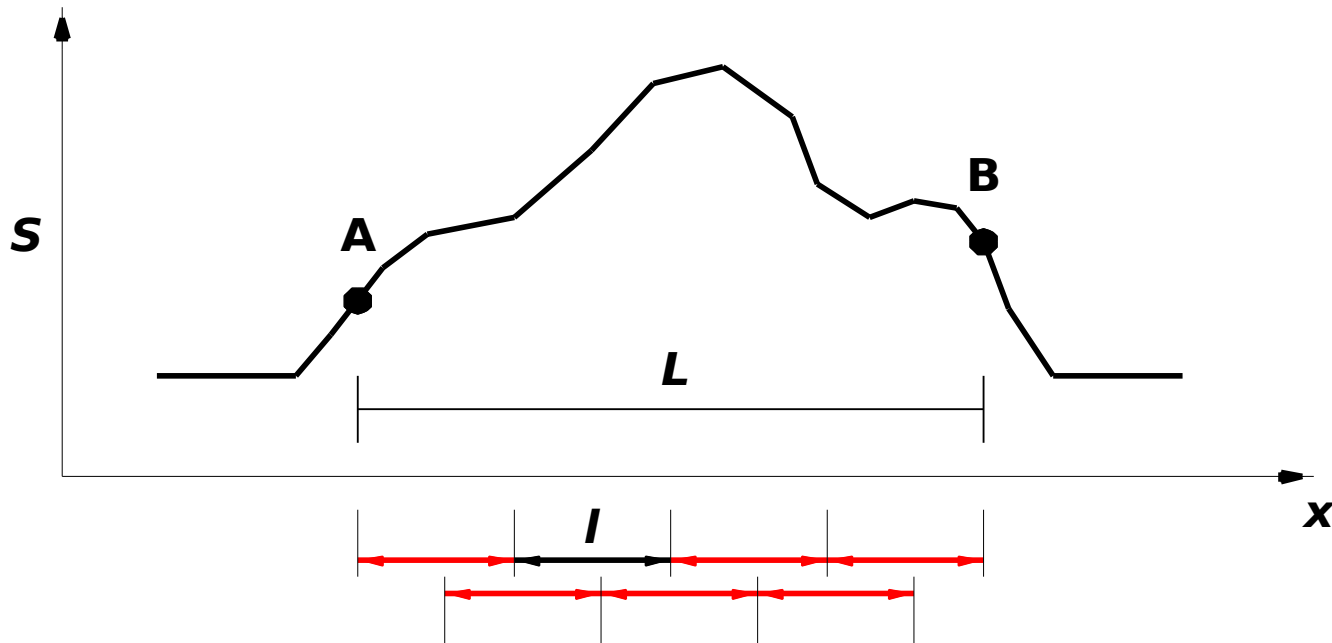
**2-D Scanning  
Random Source Crossings**

# Sensitivity to Large Scales



# Sensitivity to Large Scales

$$\sigma_L \approx \left(1 + \frac{L}{l}\right)^{1/2} \sigma_0$$



**Scanning Wide**

# Dynamic Range

*Ground-Based, High-Background Instrumentation*

## **DOCTOR'S WARNING!**

**Avoid observing modes where changing of background can dwarf astronomical signals.**

~~Secondary Movement~~

~~Calibrator Blades~~

# Design Criteria

---

- (1) **Faster** is Better!
  - (2) **2D** Scanning.
  - (3) **Random** Source Crossings in Time-streams.  
(non-repeating patterns...)
  - (4) **Wide Strokes** matching the Largest Faint Structures.
- 
- (5) Scanning with **Primary** (for ground-based submm).
  - (6) **Connected** Patterns (settling time overheads).
  - (7) **No Sharp Turns** (acceleration overload).

# What's Wrong with Staring?

## Detector Noise Limited

$$\sigma_{\text{det}} > \sigma_{\text{bg}}$$

Dark Frame Calibration Time

=

On-Source Time

**4 x overhead!!!**

## Heavily Background Limited

$$\sigma_{\text{det}} \ll \sigma_{\text{bg}}$$

Dark Frame Calibration Time

$\ll$

On-Source Time

**small overhead**

Space-based and airborne sub-mm  
and far-infrared instrumentation

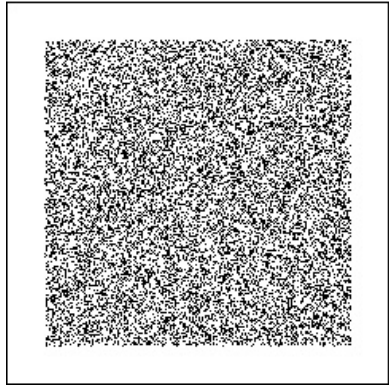
Ground-based sub-mm  
cameras

optical/IR cameras

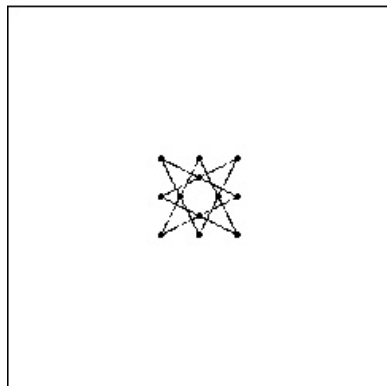
# Simulations

## Pattern Gallery

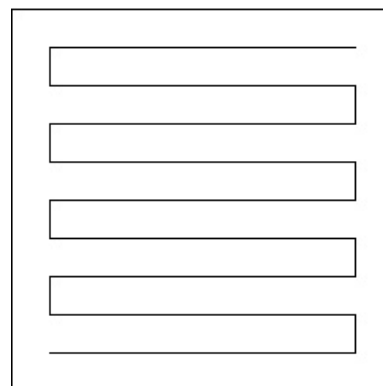
random



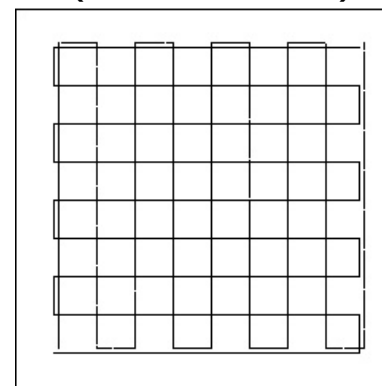
DREAM



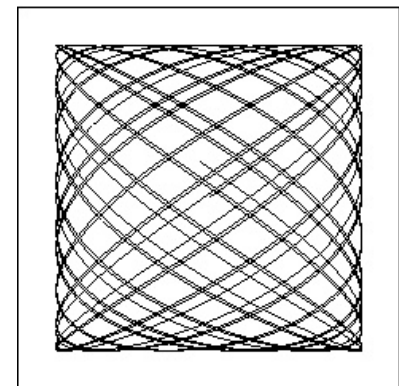
OTF



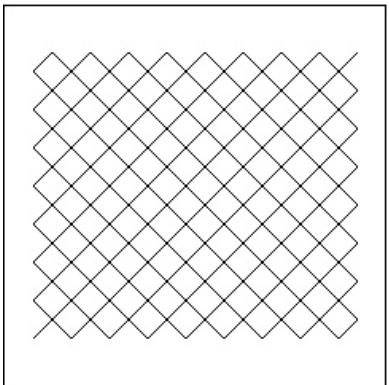
OTF  
(cross-linked)



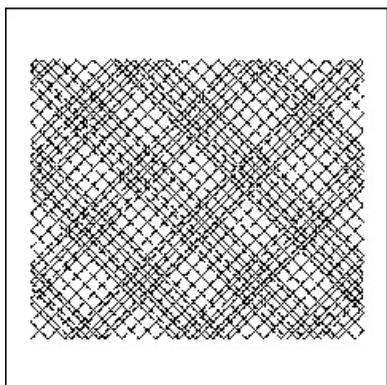
Lissajous



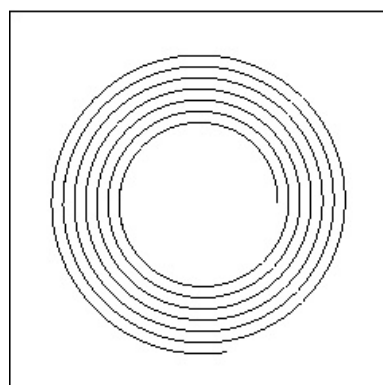
Billiard (closed)



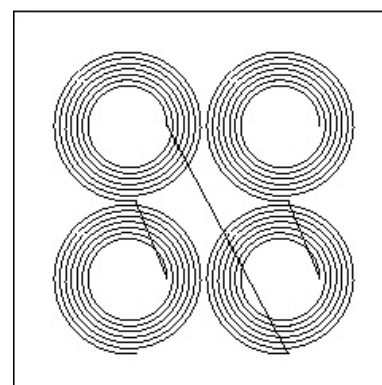
Billiard (open)



spiral



raster-spiral



... and other  
patterns...

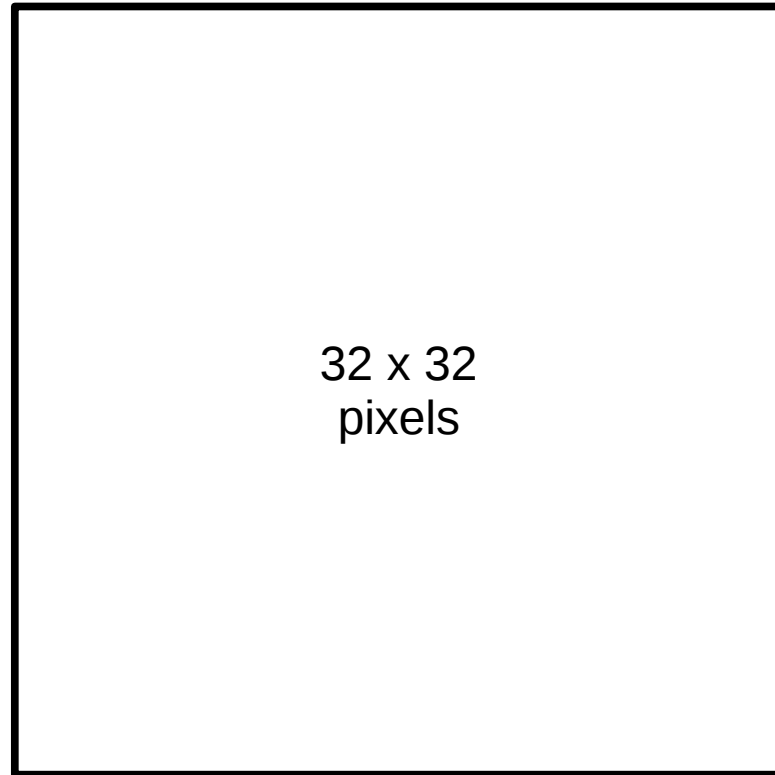
What is your  
favourite?

<http://www.submm.caltech.edu/~sharc/scanning/>



# Simulations

---

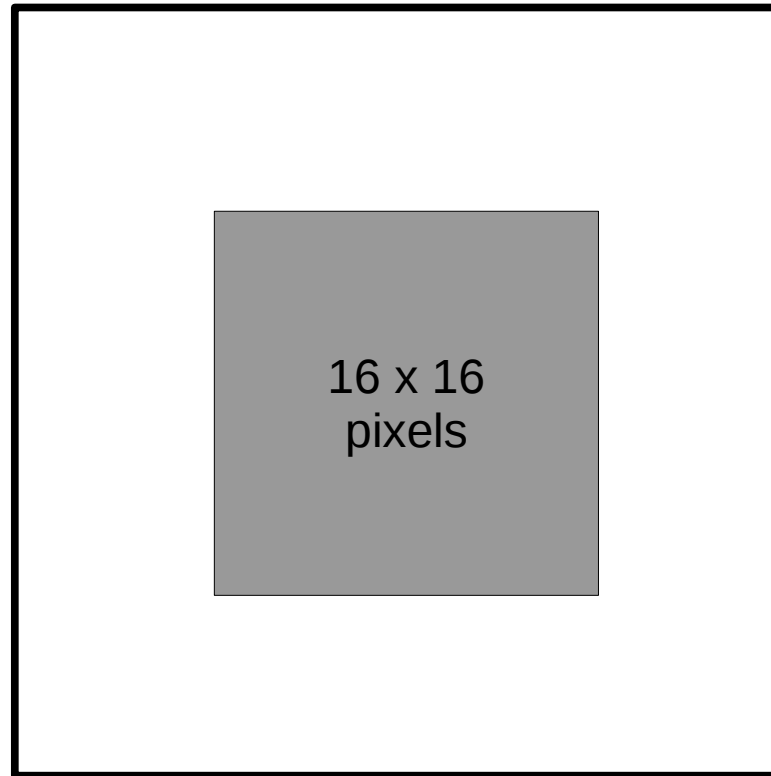


<http://www.submm.caltech.edu/~sharc/scanning/>

# Simulations

## Size

Aim to cover same area



## “Speed”

1 pixel/frame average  
scanning speed

*(1 position/frame)*

# Spectral Moments

$$m_i = \left\langle f^i \hat{P}_{f,\mathbf{F}} \right\rangle = \frac{\sum_f \sum_{\mathbf{F}} f^i \hat{P}_{f,\mathbf{F}}}{\sum_f \sum_{\mathbf{F}} f^i}$$

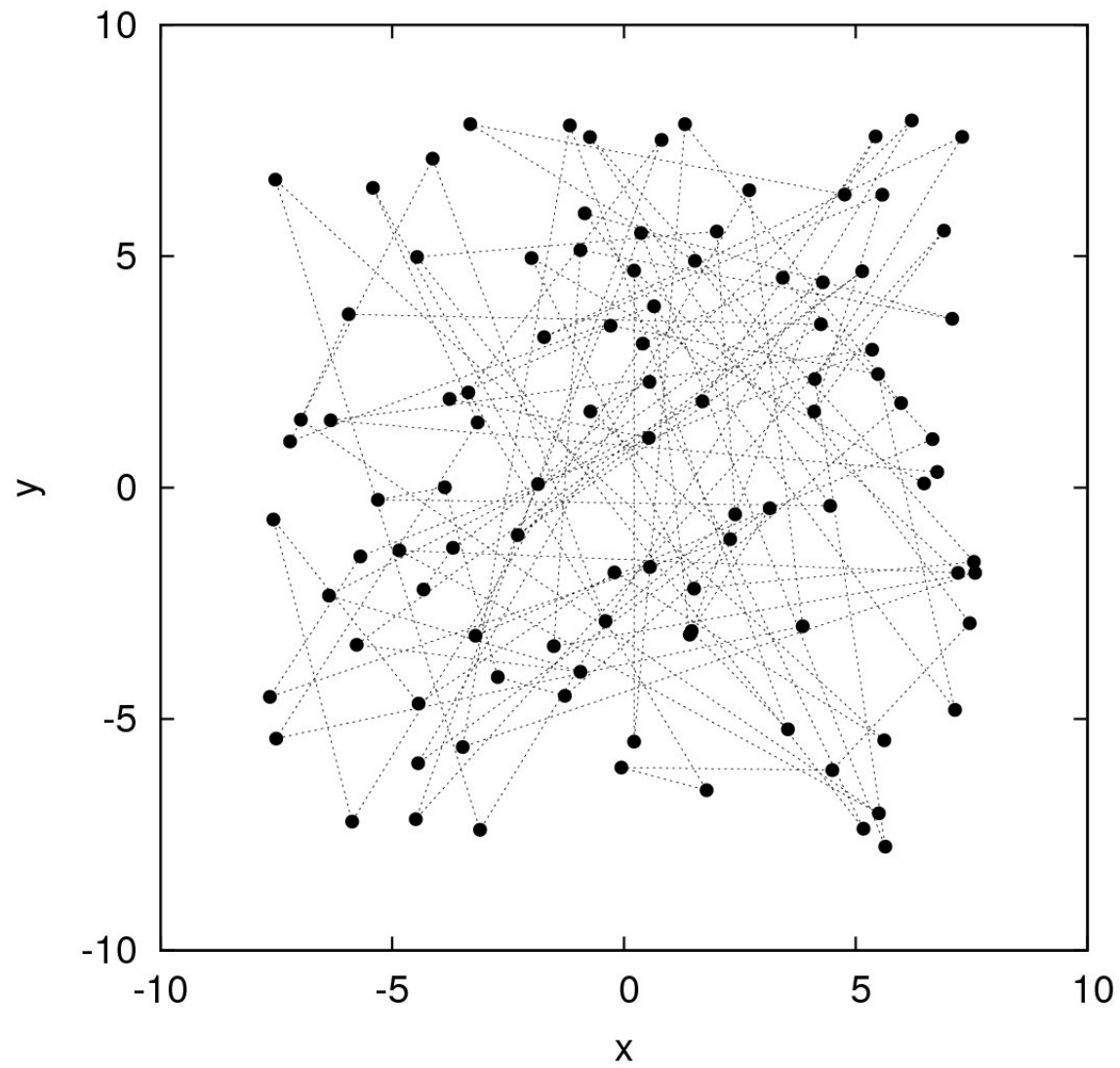
$m_0$ : The fraction of phase space volume occupied by a point source observed with the pattern.

$m_1$ : Resistance against canonical  $1/f$  noise (electronics)

$m_2$ : Resistance against  $1/f^2$  noise (atmosphere + temperature fluctuations)

$m_1, m_2$ : Also large-scale sensitivity indicators...

# Random

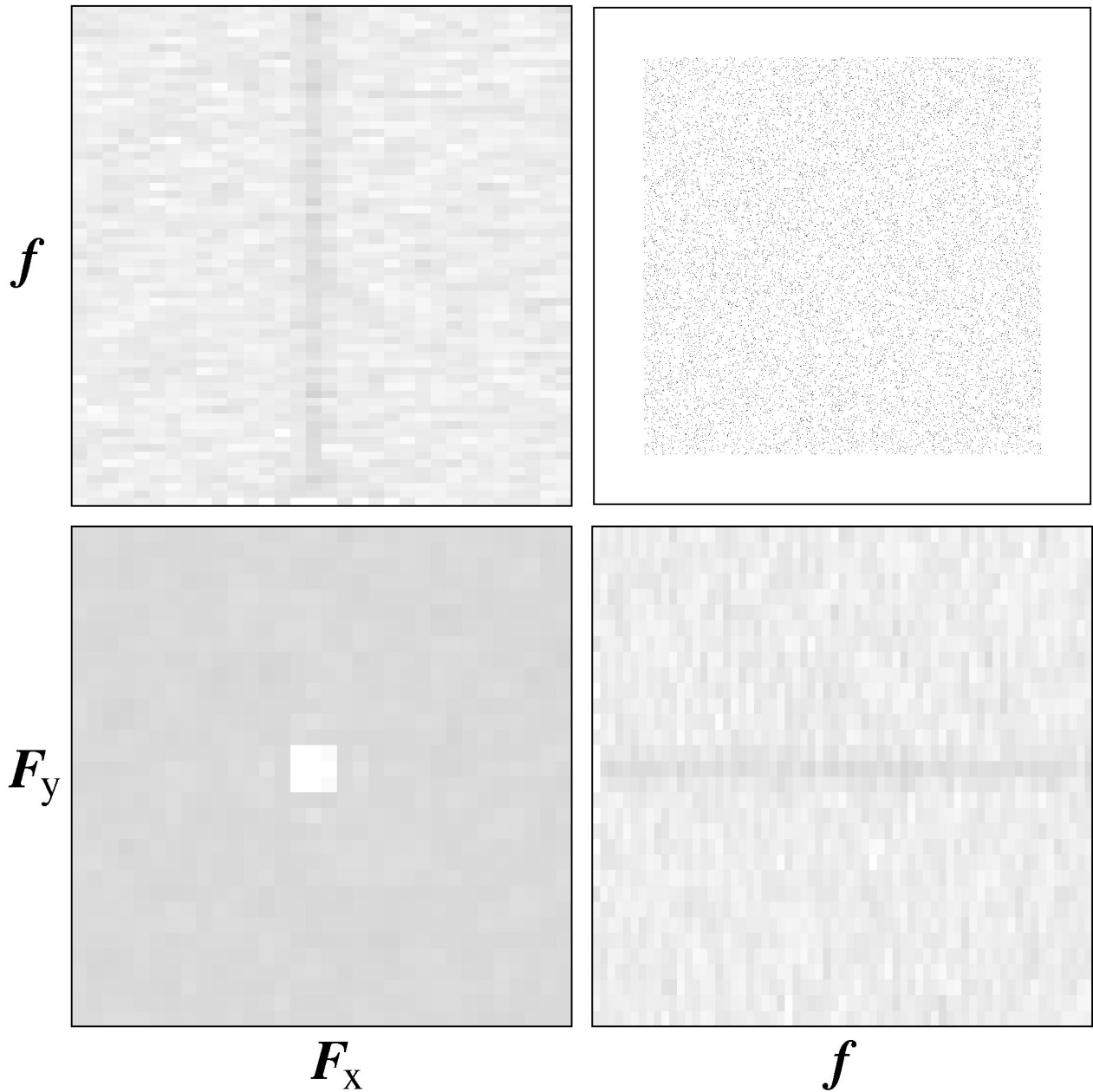


# Random

$$m_0 = 1.000$$

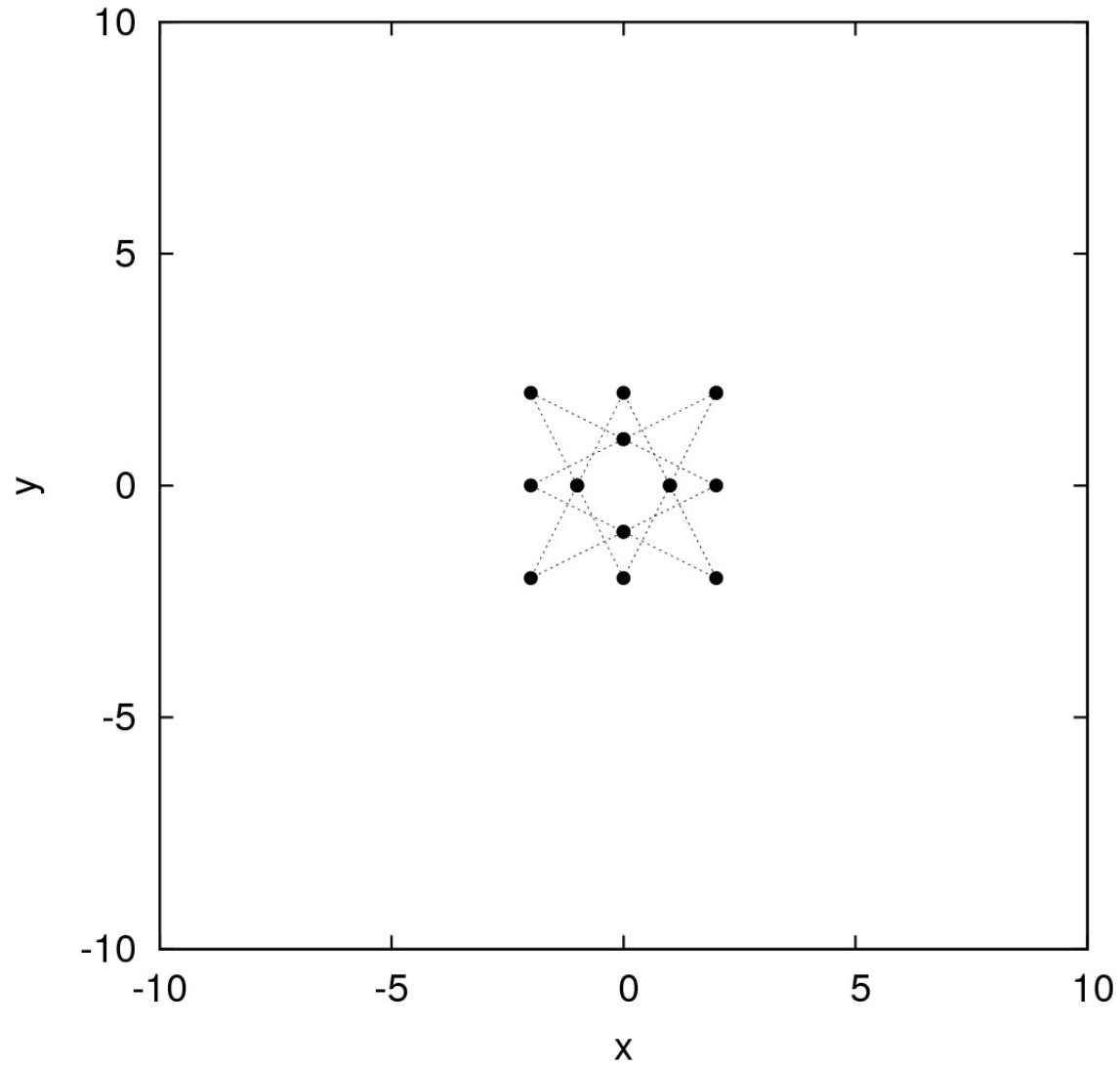
$$m_1 = 1.000$$

$$m_2 = 1.000$$



# DREAM

*Dutch Real-Time Acquisition Mode*



# DREAM

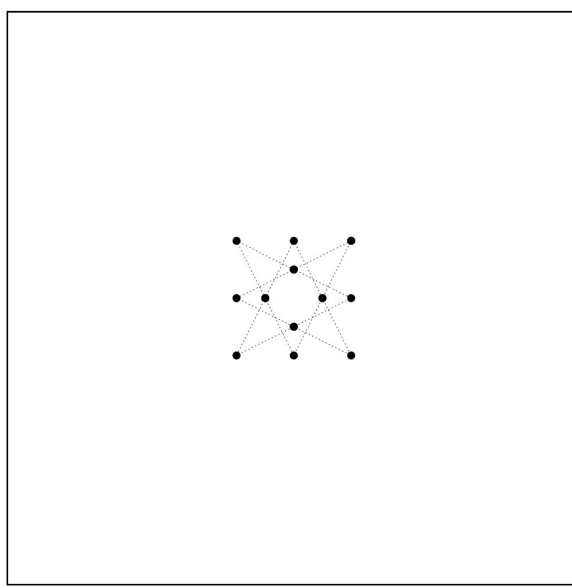
## *Dutch Real-Time Acquisition Mode*

$$m_0 = 0.0018$$

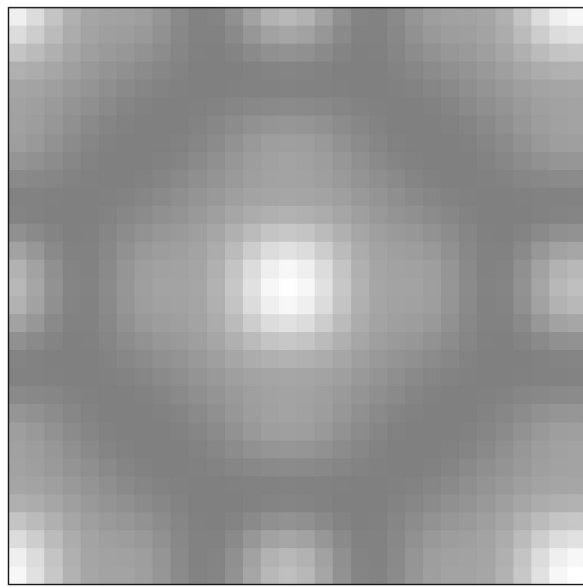
$$m_1 = 0.0018$$

$$m_2 = 0.0019$$

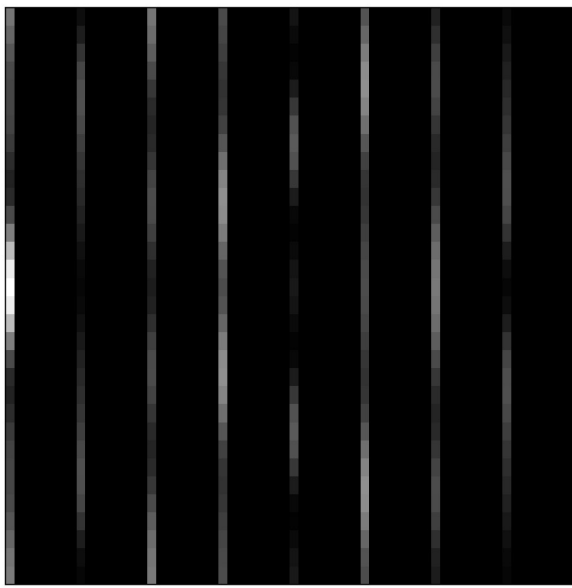
$f$



$F_y$



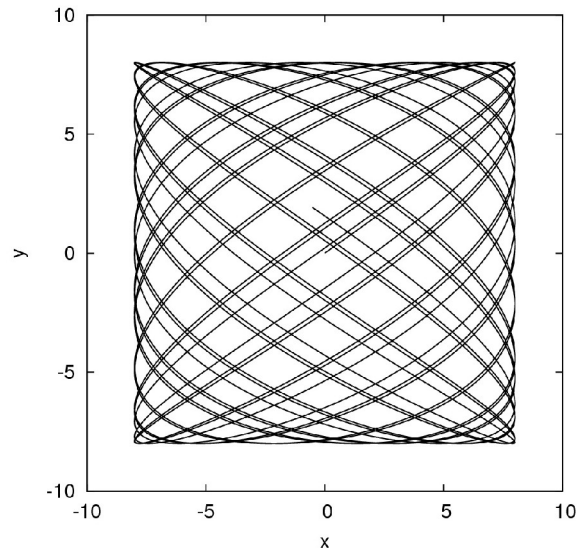
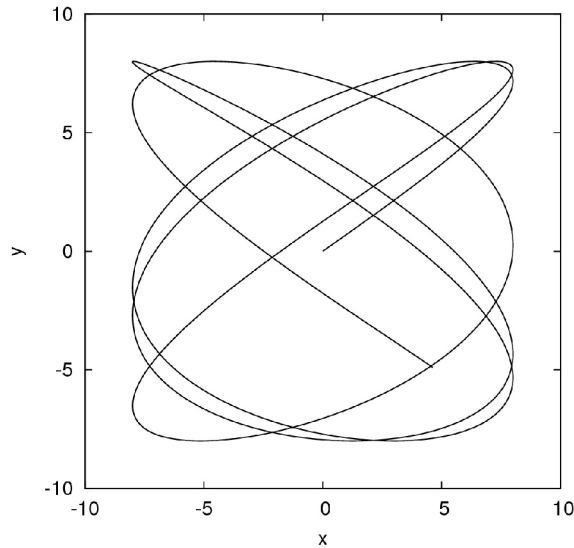
$F_x$



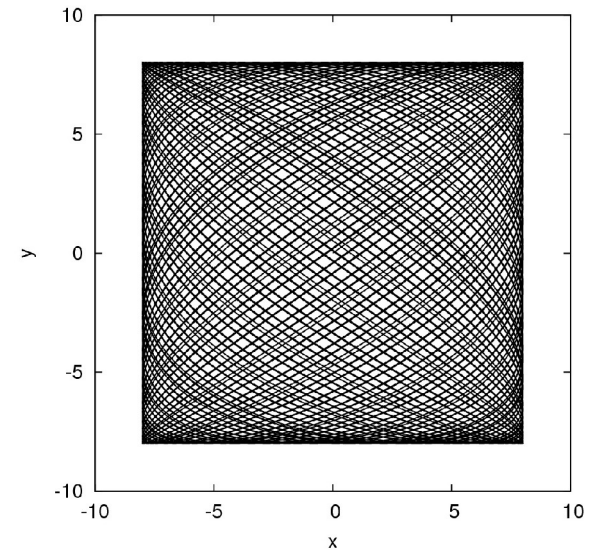
$f$

# Lissajous

Used for SHARC-2 FoV mapping since 2003.



Irrational x and y frequencies lead to non-repeating, open patterns



Edge-heavy coverage



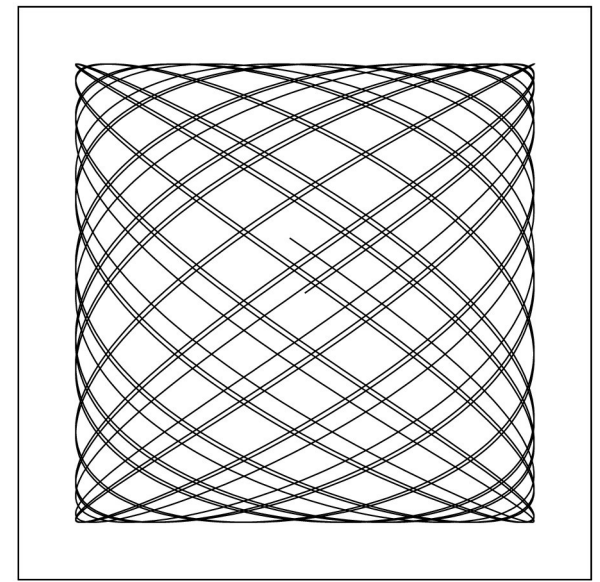
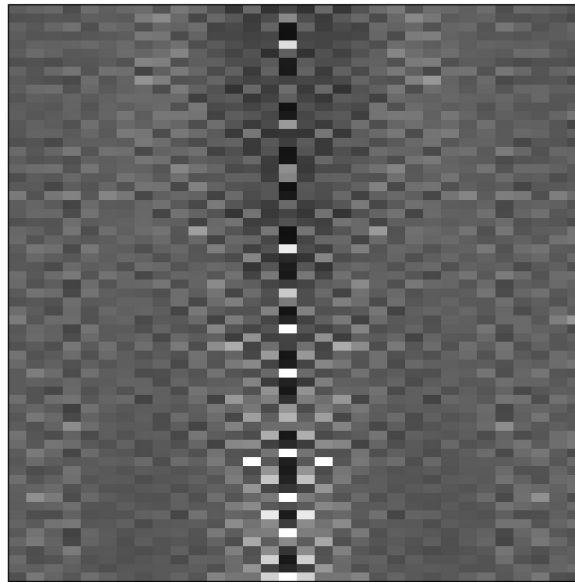
# Lissajous

$$m_0 = 0.129$$

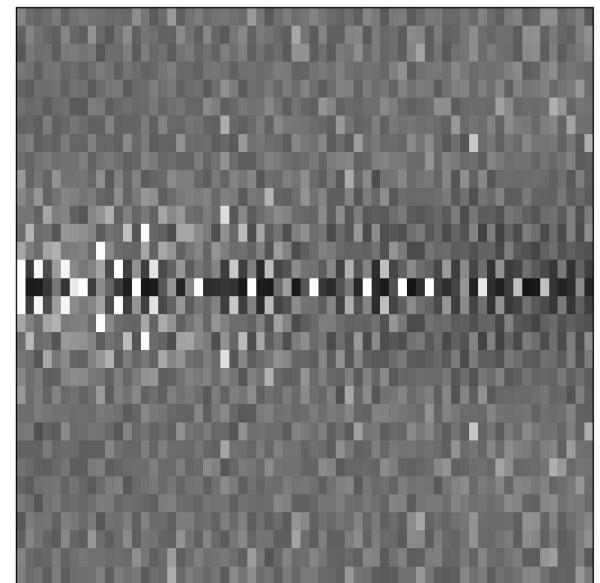
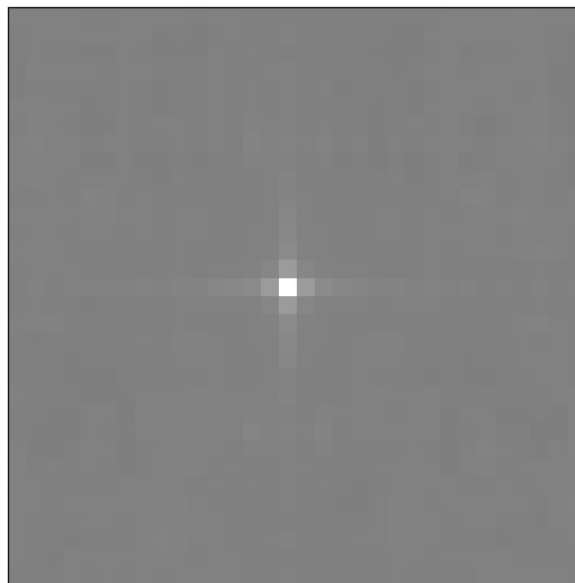
$$m_1 = 0.126$$

$$m_2 = 0.125$$

$f$



$F_y$



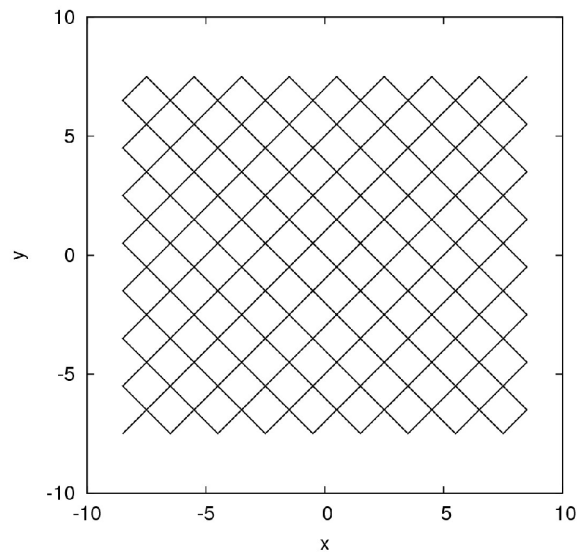
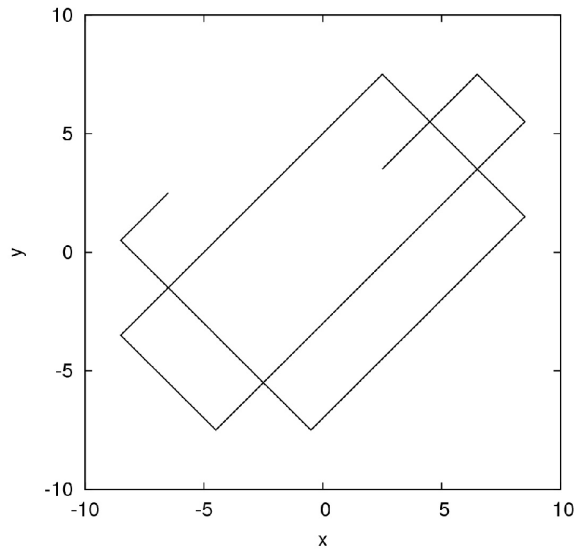
$F_x$

$f$

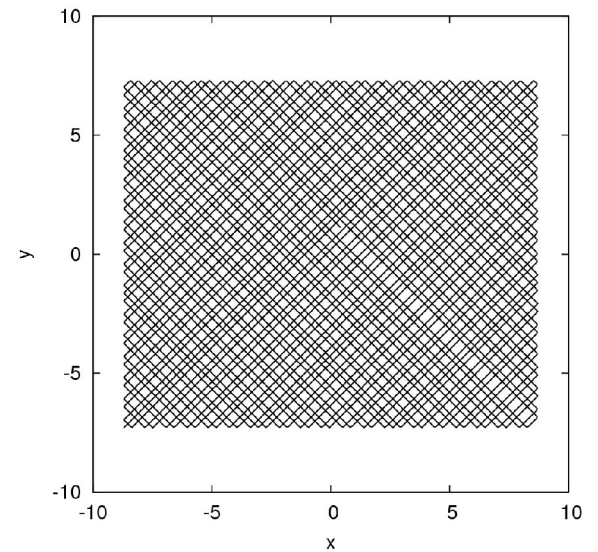
# Billiard Scan

*a.k.a. 'PONG' and 'box-scan'*

Used for SHARC-2 large-field mapping since 2003 (Borys & Dowell).



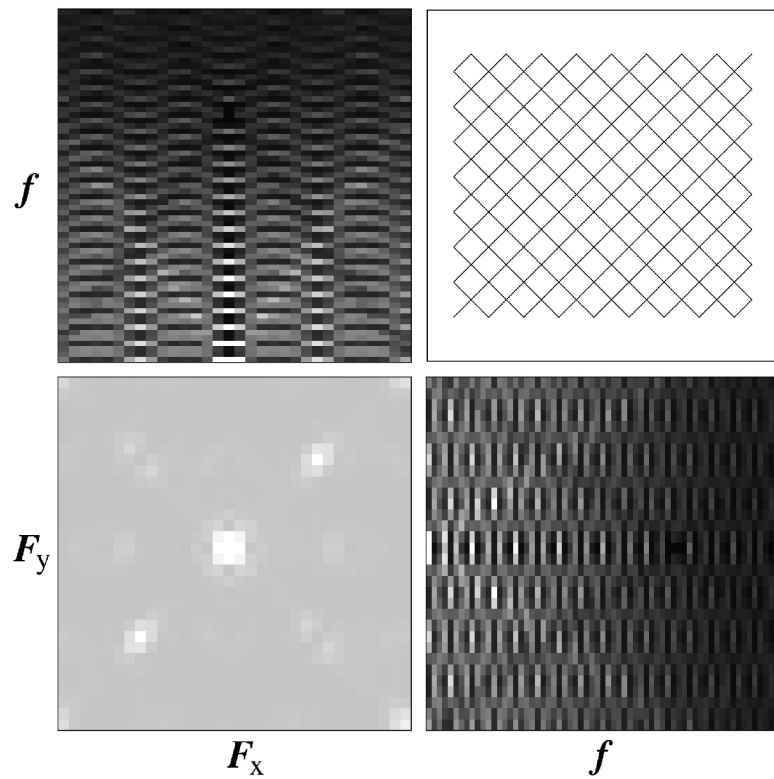
Rational x and y  
frequencies lead to  
closed patterns



Irrational x and y  
frequencies lead to  
non-repeating,  
open patterns

# Billiard Scan (closed)

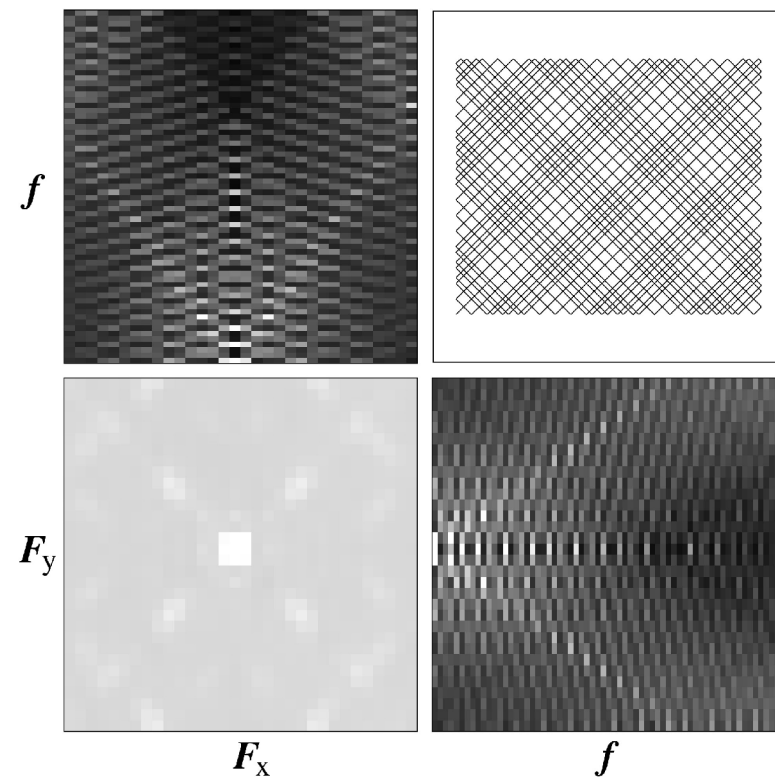
*a.k.a. 'PONG' and 'box-scan'*



$$m_0 = 0.091$$

$$m_1 = 0.068$$

$$m_2 = 0.058$$



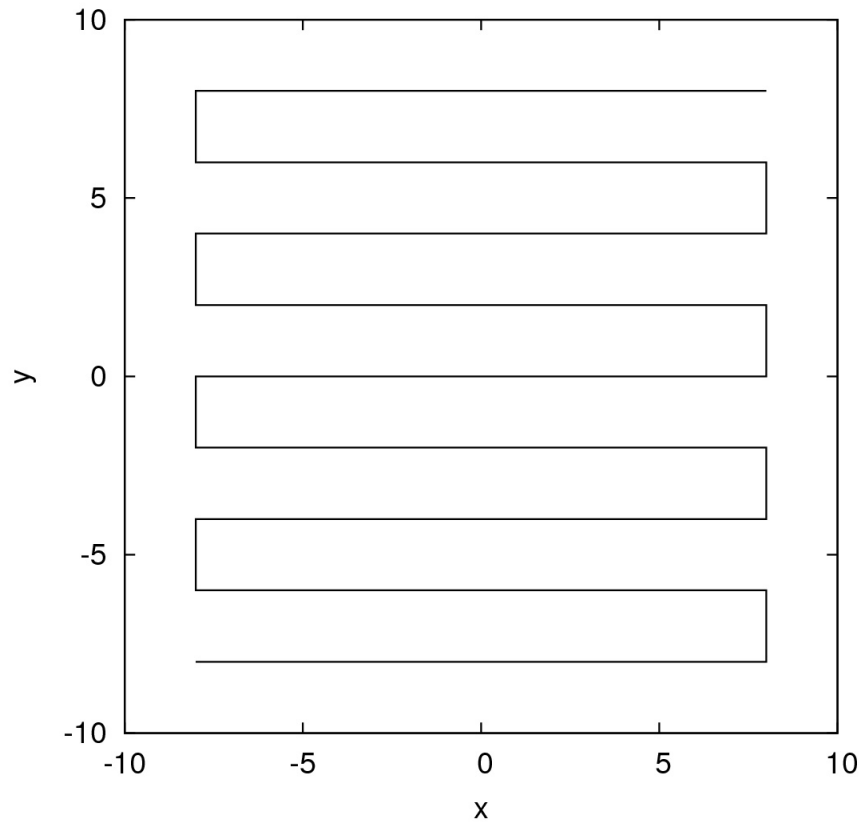
$$m_0 = 0.097$$

$$m_1 = 0.089$$

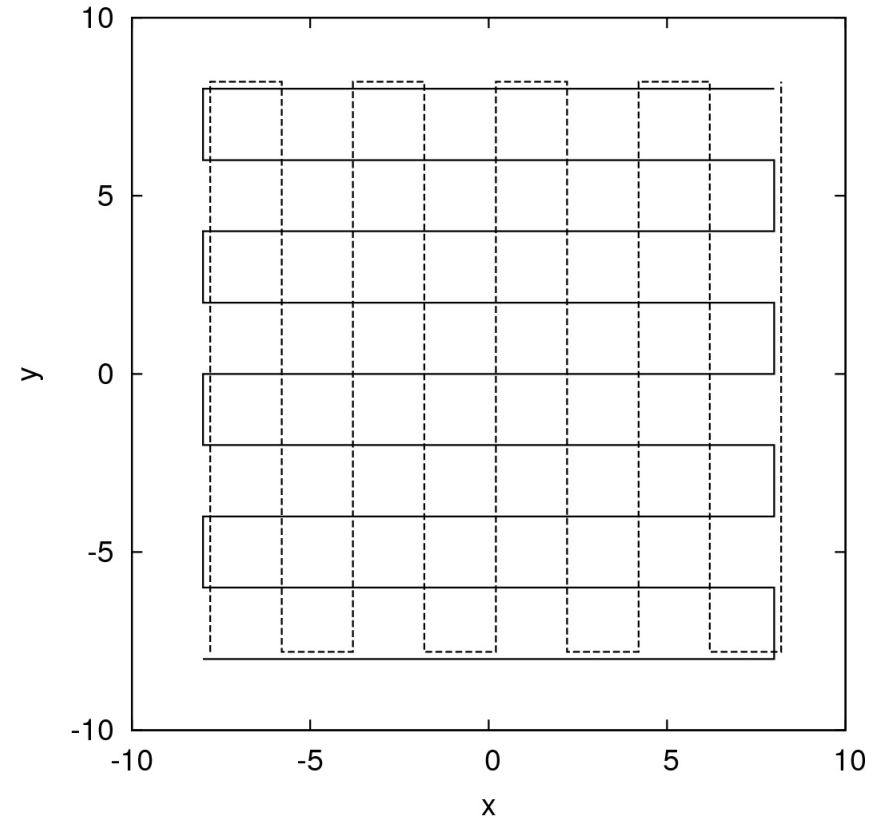
$$m_2 = 0.086$$

# On-The-Fly (OTF) Scanning

*a.k.a. 'Serpentine' or 'Raster Scan'*



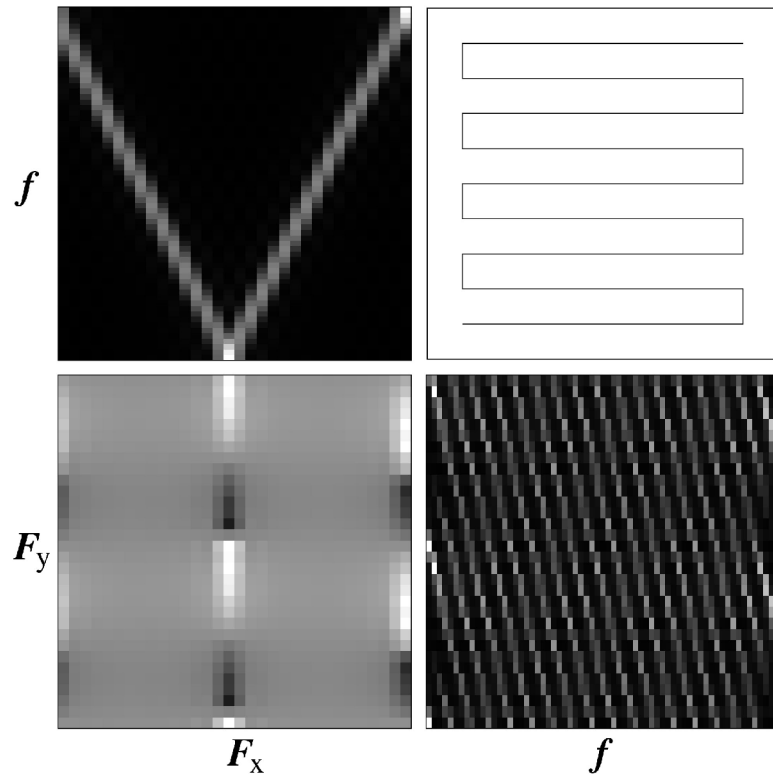
Directional Sensitivity  
to Large Scales...



Cross-linked at 90 deg  
for better large scale sensitivity  
in both directions

# On-The-Fly (OTF) Scanning

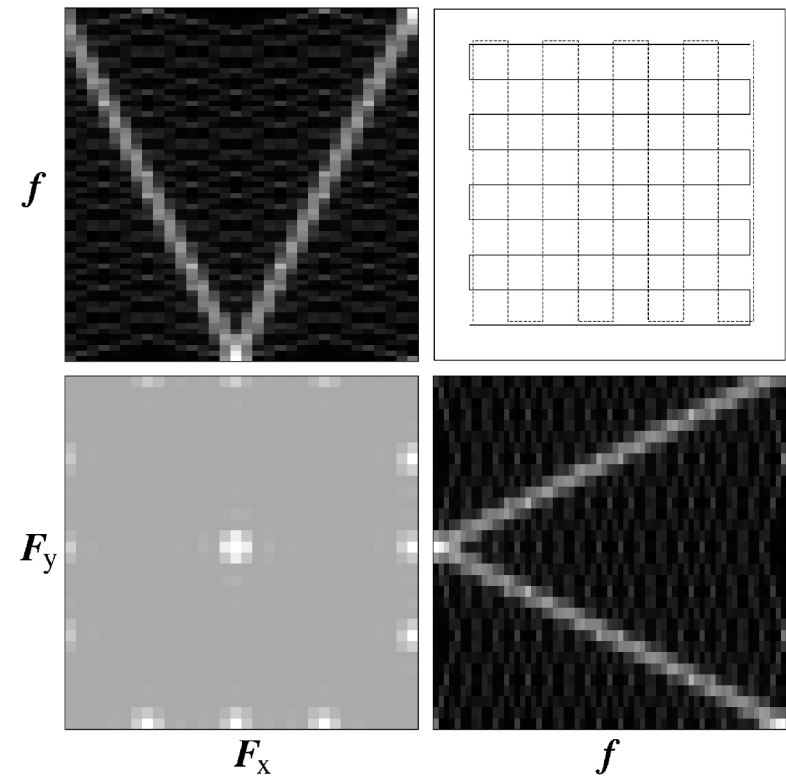
*a.k.a. 'Serpentine' or 'Raster Scan'*



$$m_0 = 0.018$$

$$m_1 = 0.018$$

$$m_2 = 0.018$$



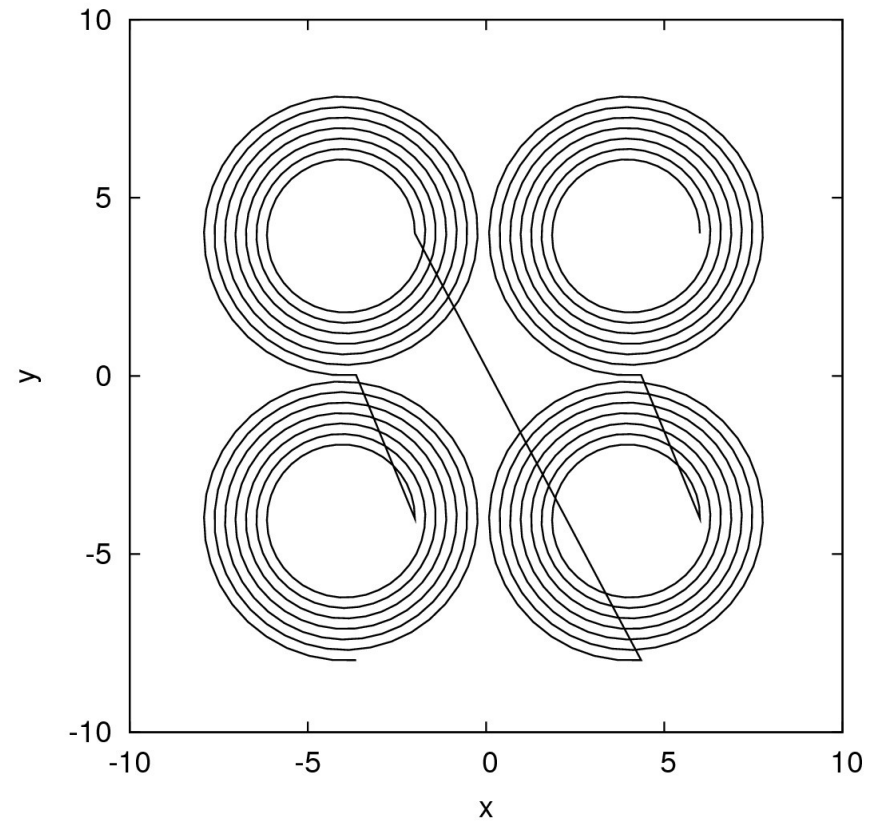
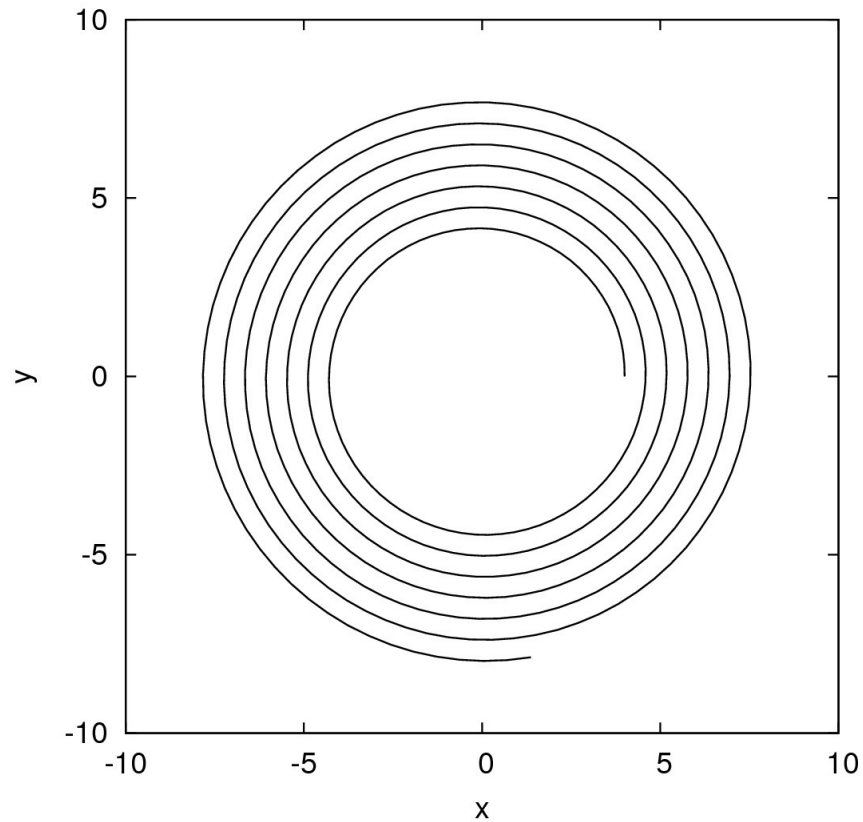
$$m_0 = 0.035$$

$$m_1 = 0.035$$

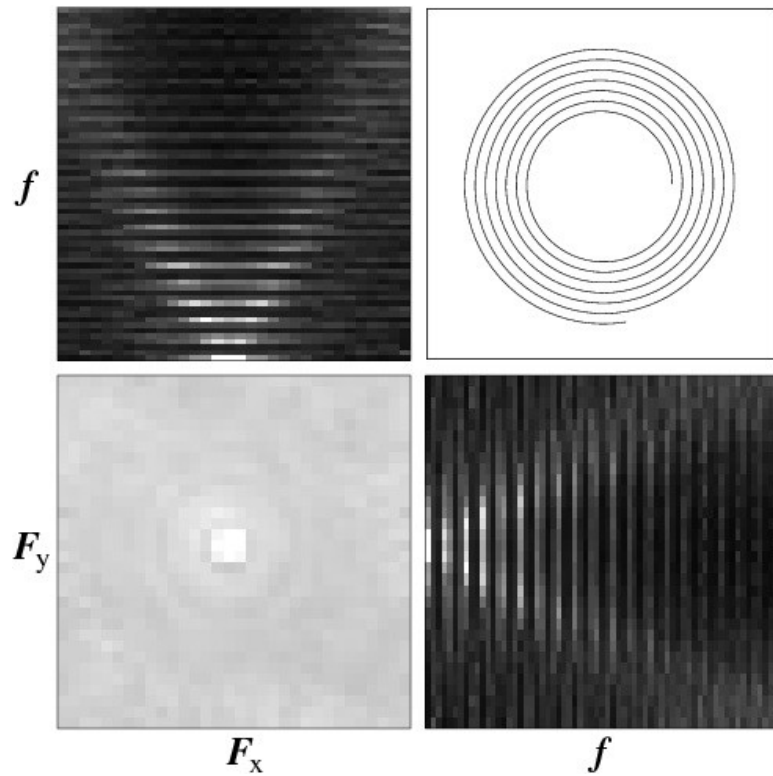
$$m_2 = 0.035$$

# Archimedean Spirals

Used at the APEX telescope in Chile for *LABOCA* Mapping



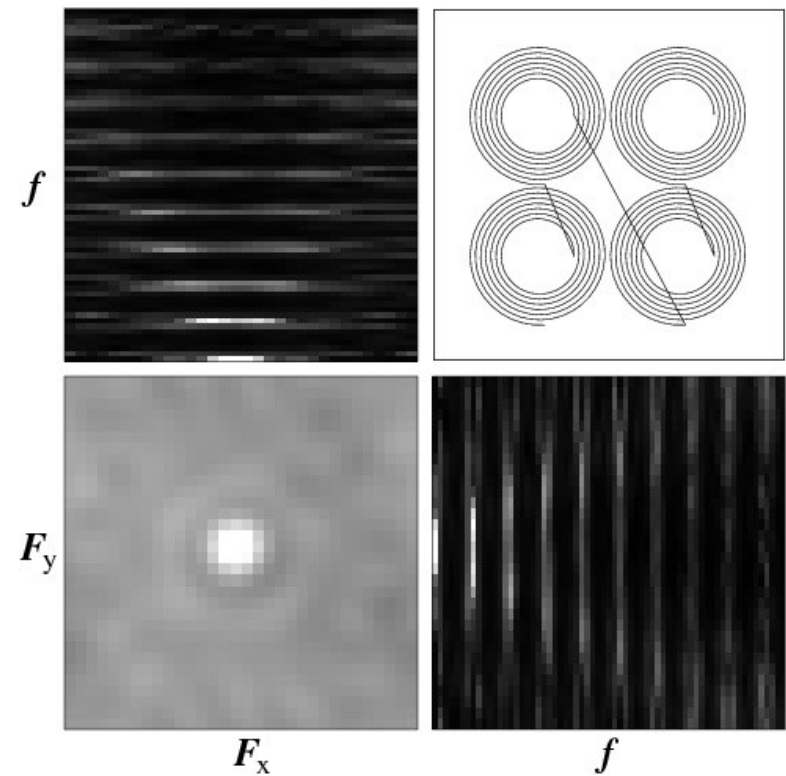
# Archimedean Spirals



$$m_0 = 0.061$$

$$m_1 = 0.056$$

$$m_2 = 0.054$$



$$m_0 = 0.080$$

$$m_1 = 0.073$$

$$m_2 = 0.070$$

# Score Card

Pattern	Geometric Parameters	Moments			$l_c$	Comments
		$m_0$	$m_1$	$m_2$		
random	$a, b$	1.000	1.000	1.000	$a, b$	discrete, unfeasible(?)
Lissajous	$A_x, A_y, \omega_y/\omega_x$	0.129	0.126	0.125	$2A_x, 2A_y$	smooth
billiard (open)	$a, b, \theta$	0.097	0.089	0.086	$a, b$	
billiard (closed)	(see above)	0.091	0.068	0.058	$a, b$	
rotating OTF	$L, \Delta, \delta\Theta$	0.088	0.085	0.084	$L$	requires several angles 0–90°
raster of spirals	$\Delta_{\text{ras}}, r_0, r_{\text{max}}$	0.080	0.073	0.070	$2r_{\text{max}}$	
spiral	$r_0, r_{\text{max}}$	0.061	0.056	0.054	$2r_{\text{max}}$	smooth
crossed OTF (90°)	$L, \Delta$	0.035	0.035	0.035	$L$	
chop	$d$	0.030	0.030	0.045	$d$	discrete, (oriented), secondary
OTF	$L, \Delta$	0.018	0.018	0.018	$\Delta, L$	strongly oriented
DREAM		0.018	0.018	0.019	4 pixels	discrete, secondary
stare		n/a	0.000	0.000	FOV	up to 4× integration time



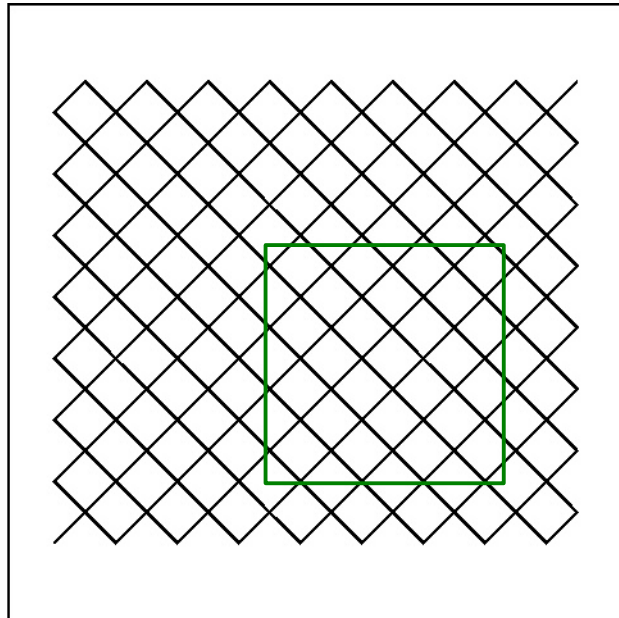
# Score Card

Pattern	Geometric Parameters	Moments			$l_c$	Comments
		$m_0$	$m_1$	$m_2$		
random	$a, b$	1.000	1.000	1.000	$a, b$	discrete, unfeasible(?)
Lissajous	$A_x, A_y, \omega_y/\omega_x$	0.129	0.126	0.125	$2A_x, 2A_y$	smooth
billiard (open)	$a, b, \theta$	0.097	0.089	0.086	$a, b$	
billiard (closed)	(see above)	0.091	0.068	0.058	$a, b$	
rotating OTF	$L, \Delta, \delta\Theta$	0.088	0.085	0.084	$L$	requires several angles 0–90°
raster of spirals	$\Delta_{\text{ras}}, r_0, r_{\text{max}}$	0.080	0.073	0.070	$2r_{\text{max}}$	
spiral	$r_0, r_{\text{max}}$	0.061	0.056	0.054	$2r_{\text{max}}$	smooth
crossed OTF (90°)	$L, \Delta$	0.035	0.035	0.035	$L$	
chop	$d$	0.030	0.030	0.045	$d$	discrete, (oriented), secondary
OTF	$L, \Delta$	0.018	0.018	0.018	$\Delta, L$	strongly oriented
DREAM		0.018	0.018	0.019	4 pixels	discrete, secondary
stare		n/a	0.000	0.000	FOV	up to 4× integration time

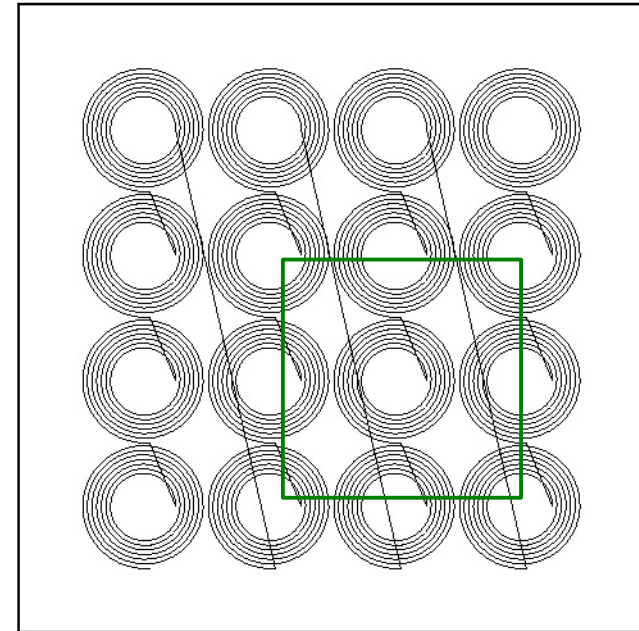
# Large Fields

*What's the best strategies for fields  $> FoV$ ?*

All at once...



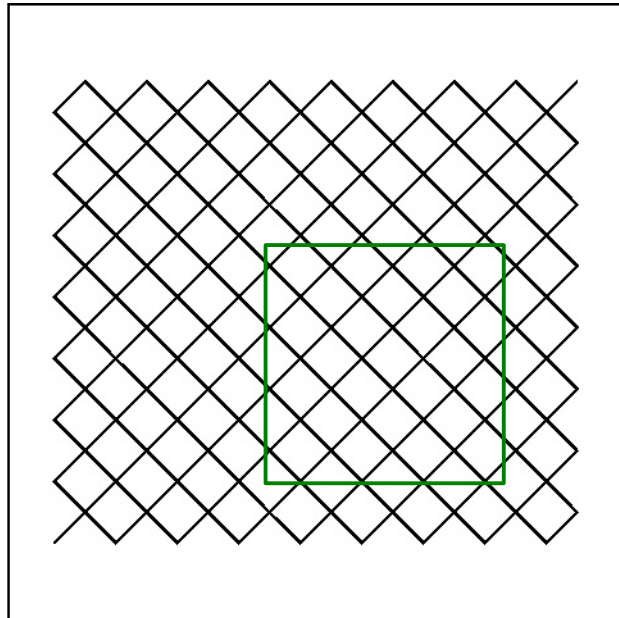
Little by little...



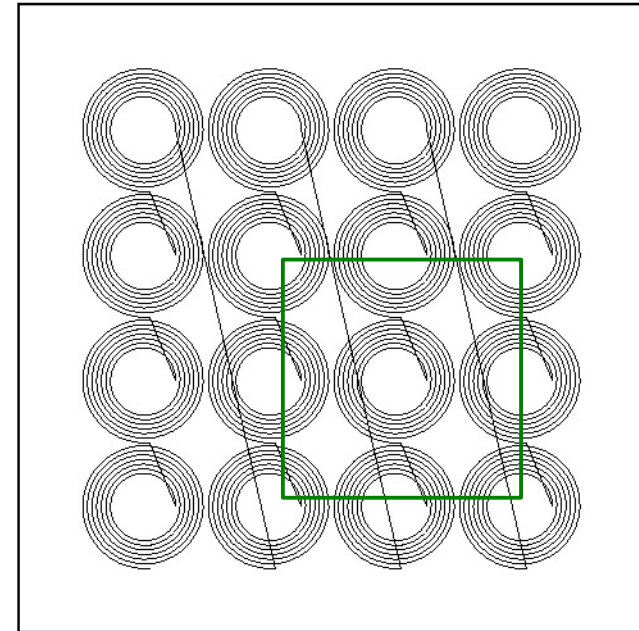
# Large Fields

*What's the best strategies for fields  $> FoV$ ?*

All at once...



Little by little...



**The answer does not depend on field size.  
It depends entirely on the pattern chosen!!!**

# Conclusions

---

## I. Recipes for Designing Better Patterns

## II. Rankings:

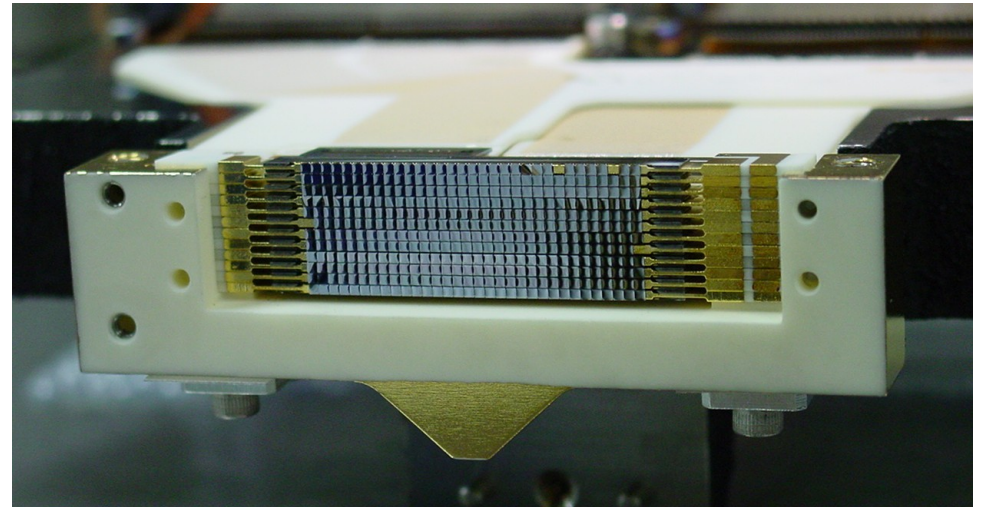
- (1) Random
- (2) Lissajous, Billiard, Spirals
- (3) Cross-Linked OTF

## III. Evaluate you own pattern at

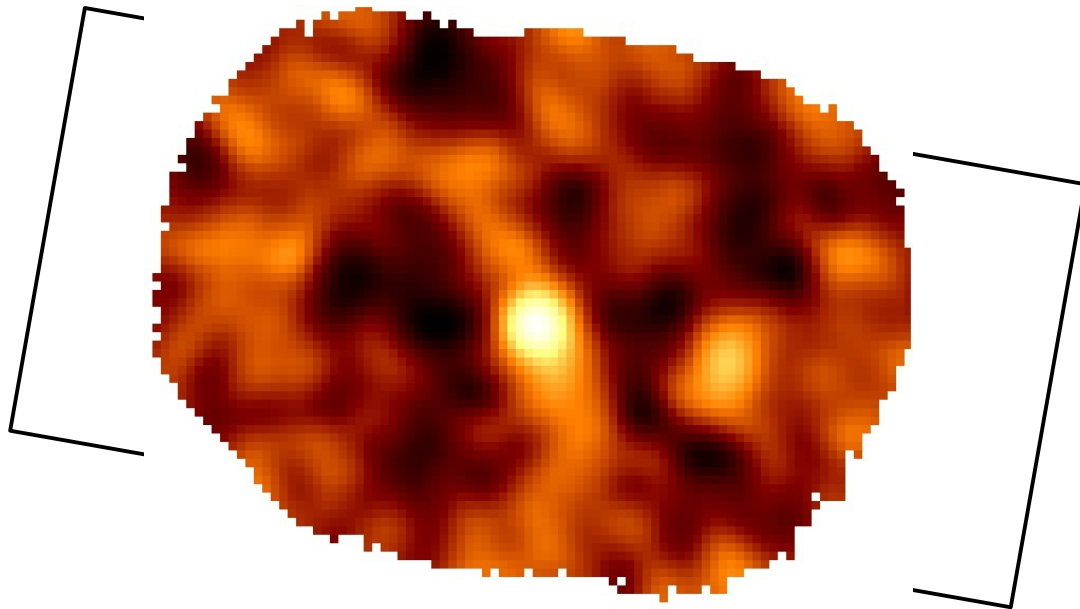
<http://www.submm.caltech.edu/~sharc/scanning>

# Lissajous

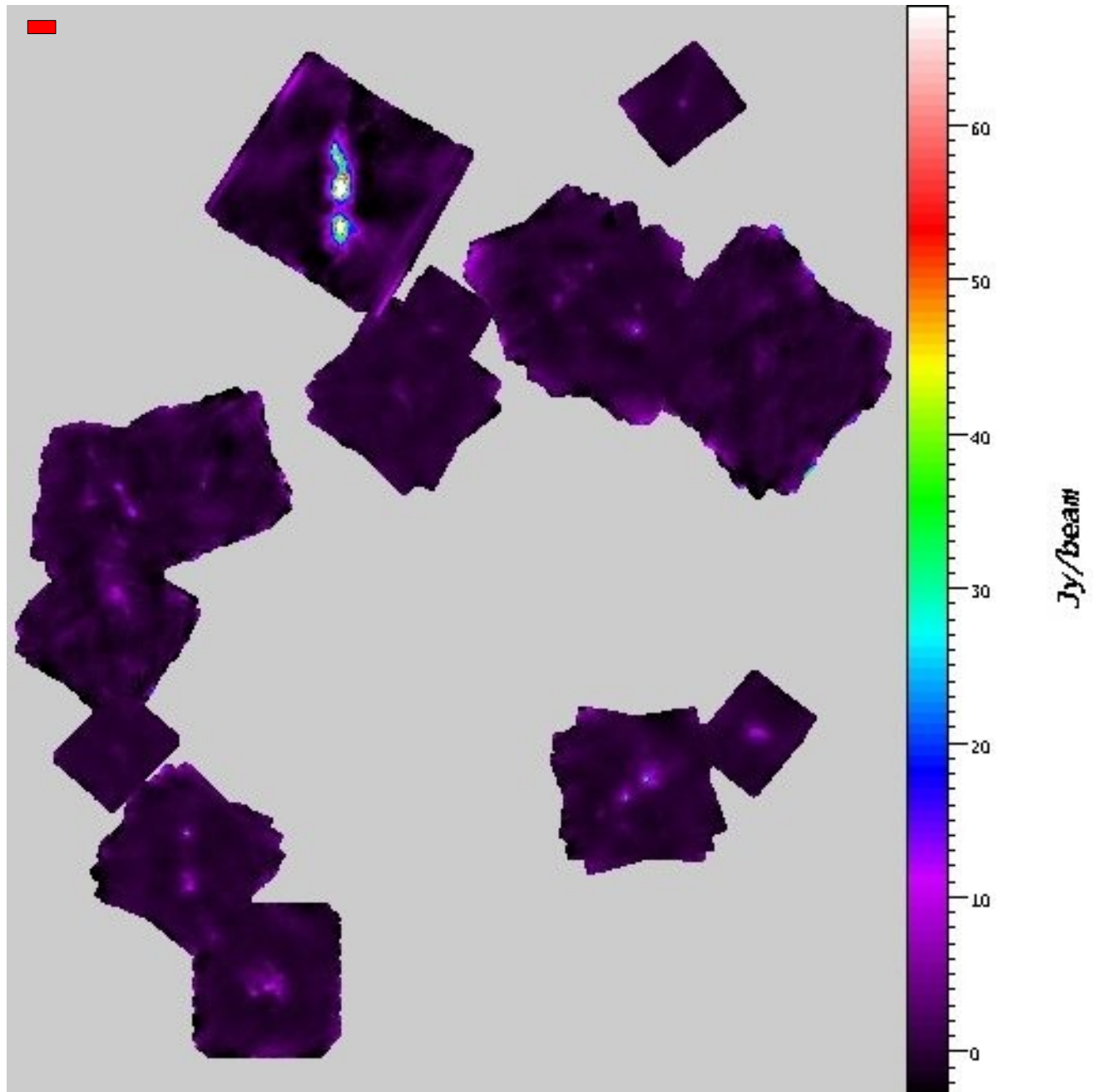
SHARC-2



SMM J163631.47 +405546.9



# Billiard

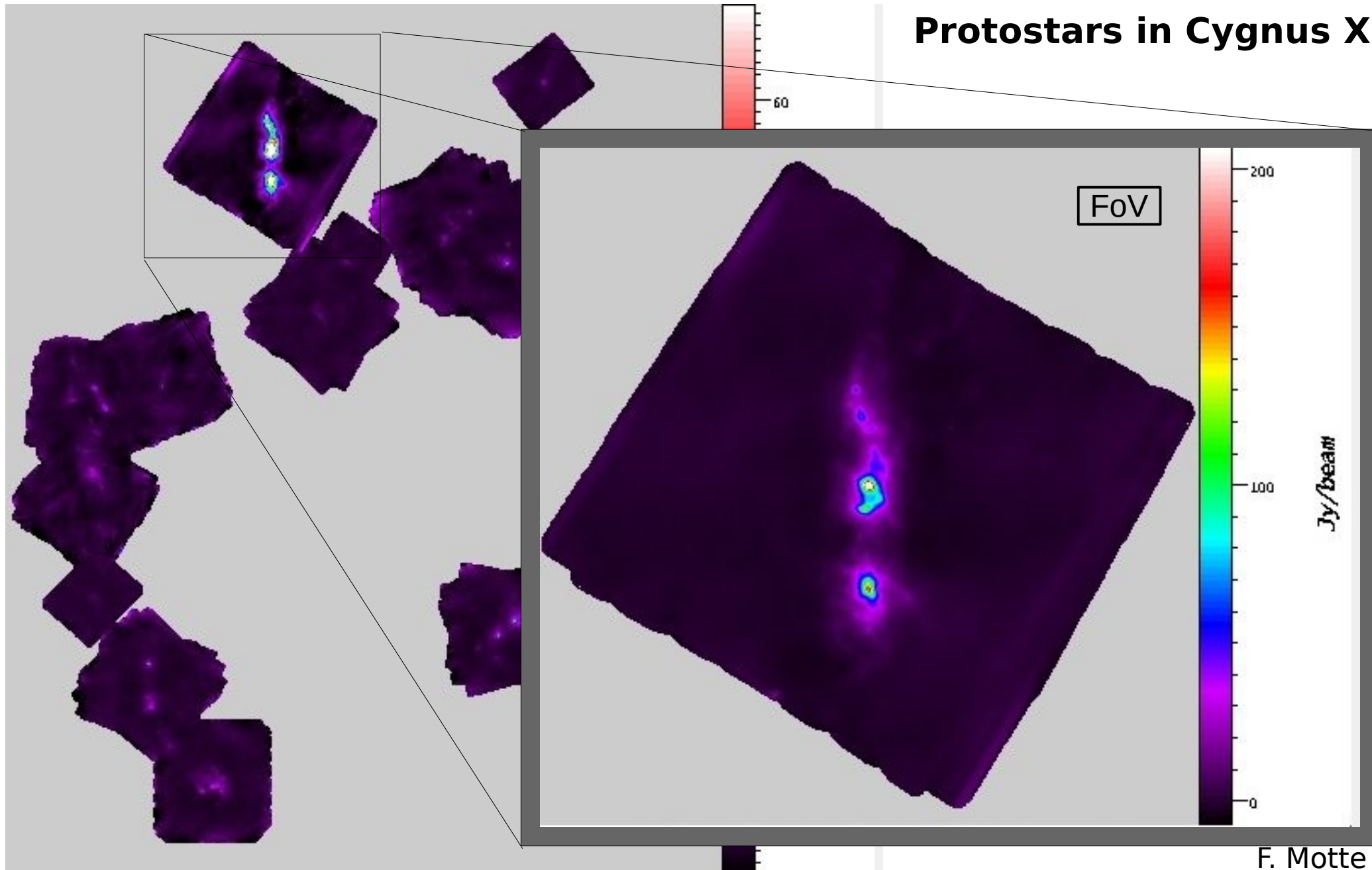


## Protostars in Cygnus X

F. Motte

# Billiard

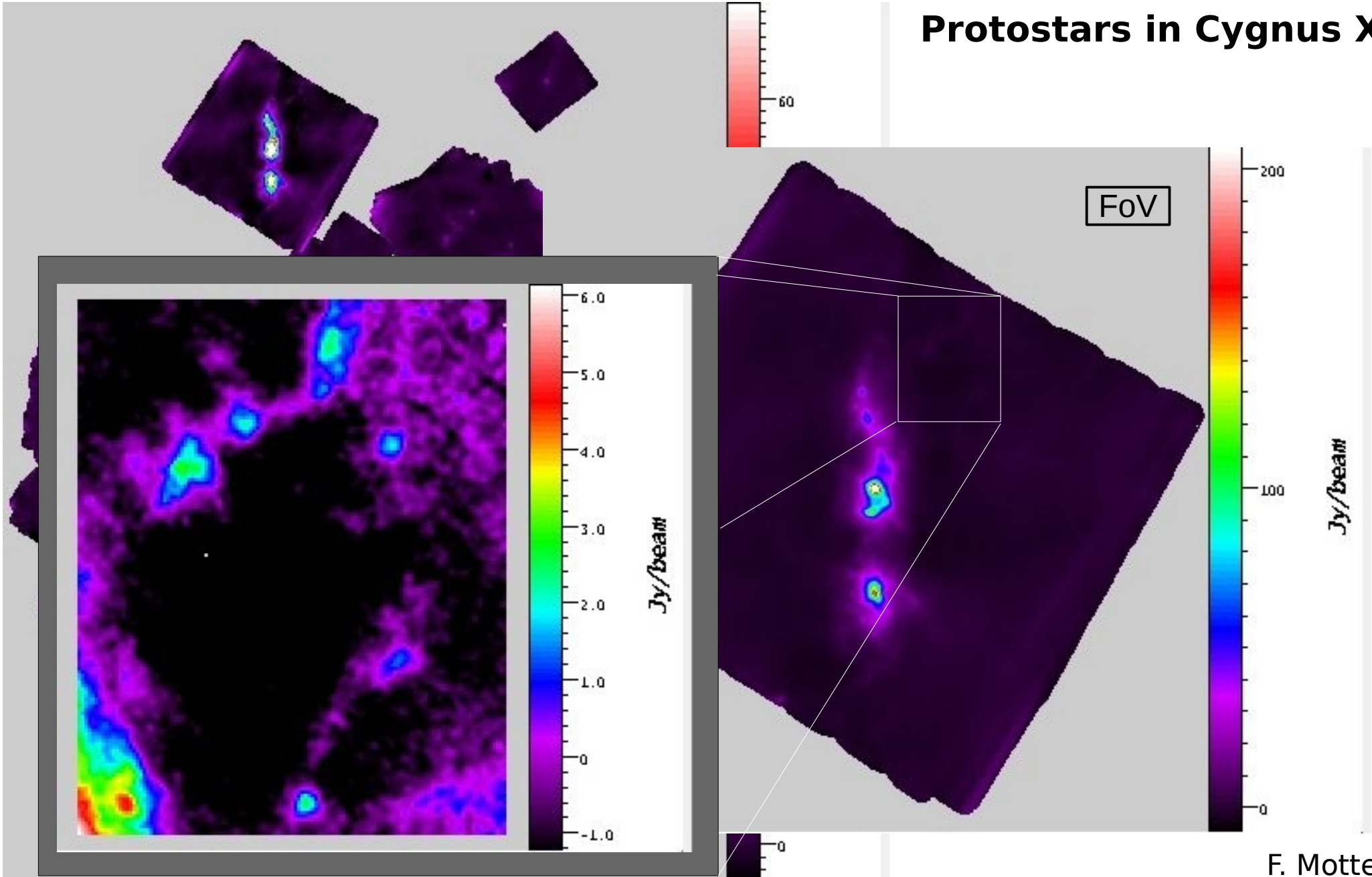
## Protostars in Cygnus X



F. Motte

# Billiard

## Protostars in Cygnus X

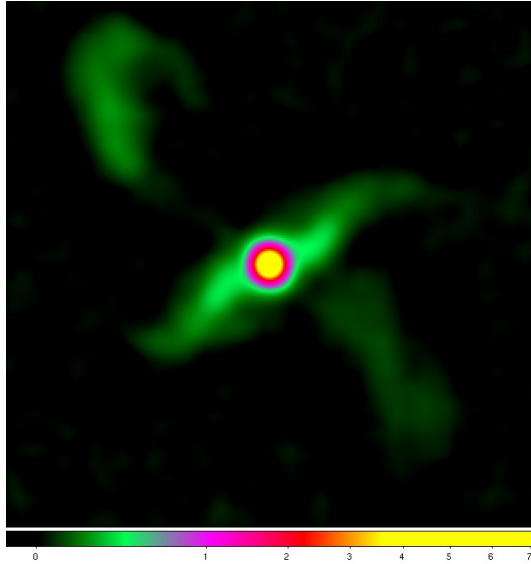


F. Motte

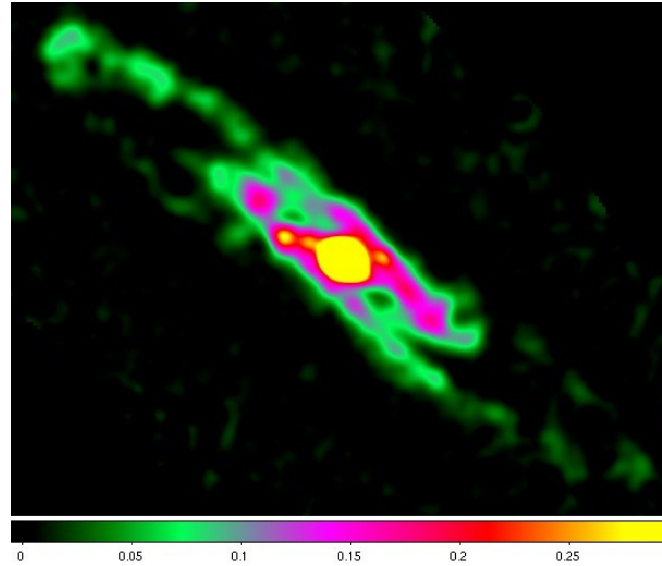


# Raster of Spirals

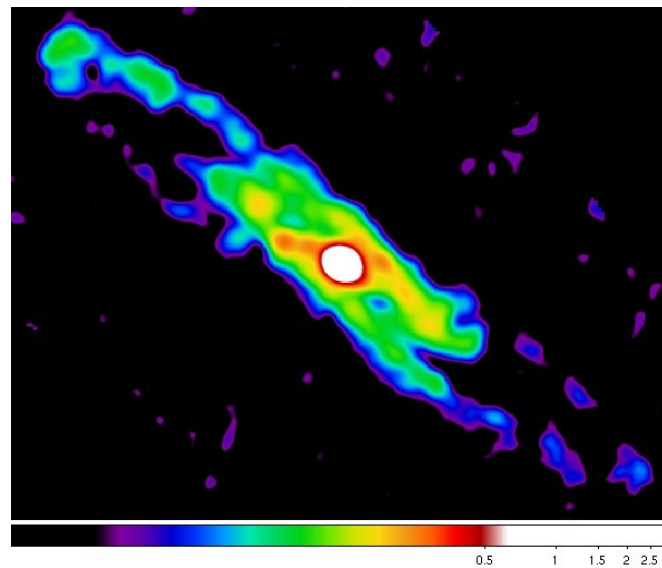
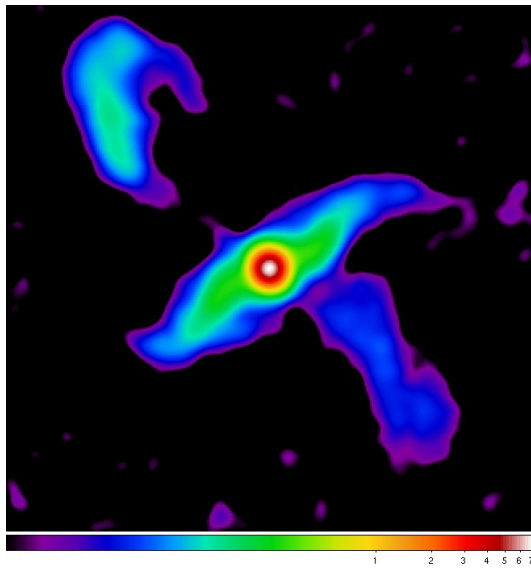
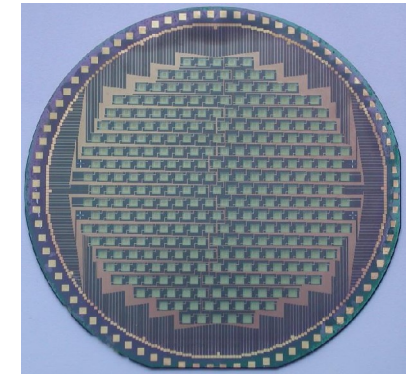
**Centaurus A**



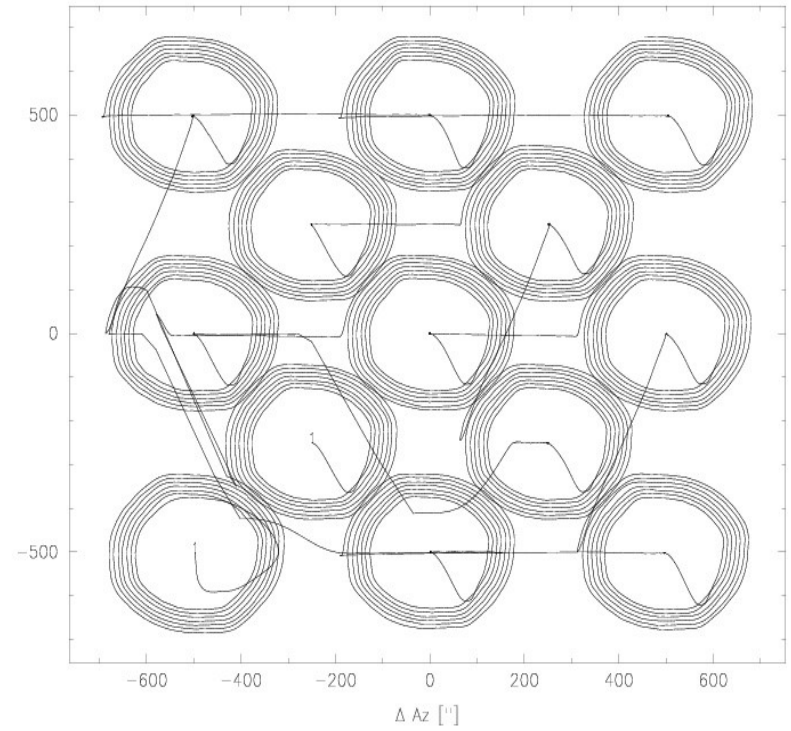
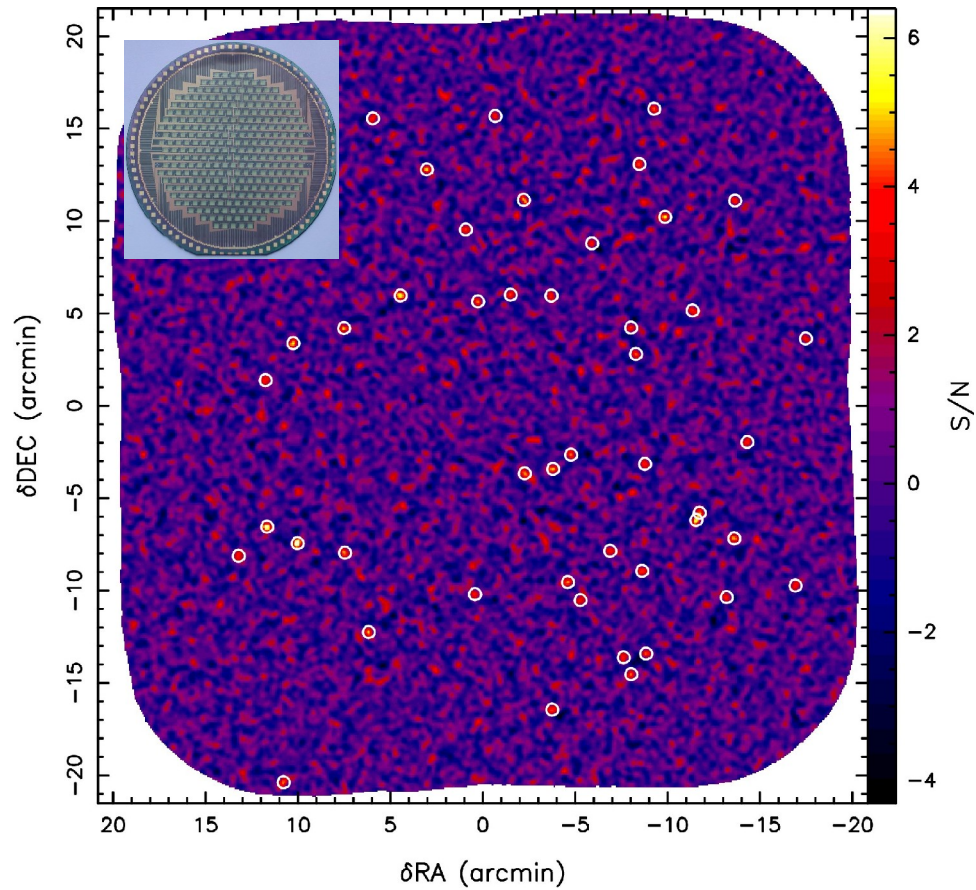
**NGC 253**



**LABOCA**



# Raster of Spirals



# Cross-Linked OTF

The Galactic Centre Region by LABOCA from the *ATLASGAL* survey

